

Lecture 07:

Classical Scheduling

CS343 – Operating Systems
Branden Ghena – Fall 2024

Some slides borrowed from:

Stephen Tarzia (Northwestern), Shivaram Venkataraman (Wisconsin), and UC Berkeley CS162

Administrivia

- PC Lab due Thursday
- Scheduling Lab should be out on Tuesday
 - Put it out early so you could get started before the exam

Midterm Exam 1

- Exam Details

- In class, Tuesday October 22. Starts at 12:30 sharp. 80-minute exam
- Covers all lectures through this week Thursday
 - (1. Introduction through 8. Scheduling: Real-Time & Modern)
- You may bring ONE 8.5"x11" sheet of paper with notes on front and back
 - Handwritten, typeset, whatever you want
- No calculators or other notes

- Review materials

- Posted to Canvas homepage: practice problems + prior exams

Today's Goals

- Introduce the concept and challenges of scheduling
- Explore scheduling for batch and interactive systems
- Identify important metrics for measuring scheduler performance
- Examine several scheduling policies that target these metrics

Outline

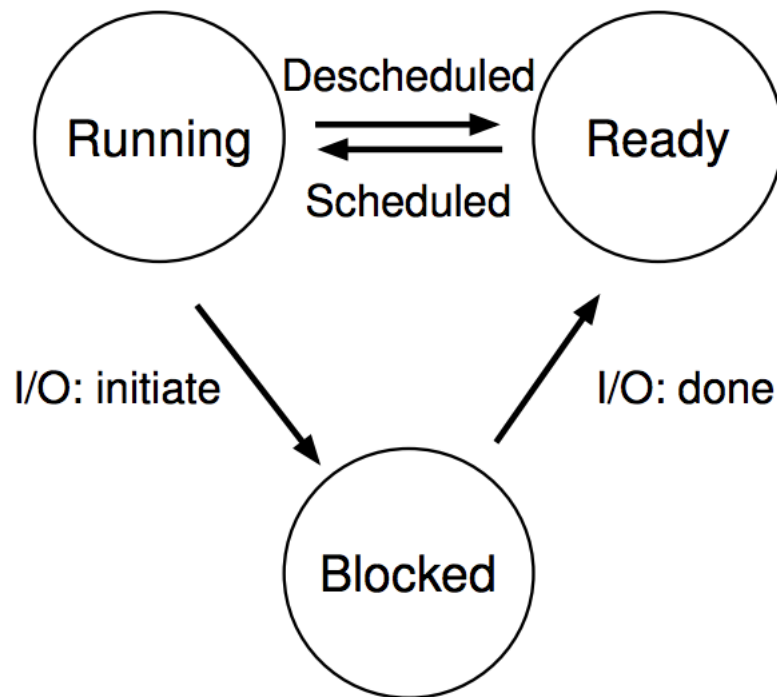
- **Scheduling Overview**
- Scheduler Metrics
- Batch Systems
 1. First In First Out scheduling
 2. Shortest Job First scheduling
 3. Shortest Remaining Processing Time scheduling
- Interactive Systems
 1. Round Robin scheduling
 2. Multi-Level Feedback Queue scheduling

Lies your operating system always told you

- “Every process on your computer gets to run at the same time!”
 - This is an *illusion*
- My desktop at home (running Windows)
 - Current load: 250 processes with 2987 threads
- So how does the magic work?

Processes don't run all the time

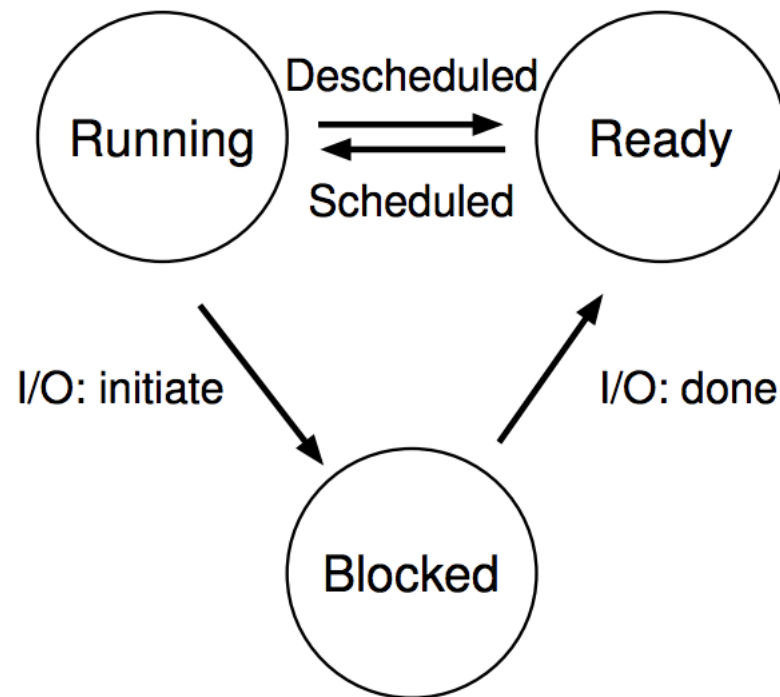
The three basic process states:



- OS *schedules* processes
 - Decides which of many competing processes to run.
- A *blocked* process is not ready to run and is waiting on I/O
- I/O means input/output – anything other than computing.
 - For example, reading/writing disk, sending network packet, waiting for keystroke, condvar/semaphore!
 - While waiting for results, the OS **blocks** the process, waiting to do more computation until the result is ready

Multiprogramming processes

The three basic process states:



- Even with a single processor, the OS can provide the illusion of many processes running simultaneously
 - And also use this opportunity to get more useful work done
- When one process is Blocked, OS can schedule a different process that is Ready
- OS can also swap between various Ready processes so they all make progress

Scheduling

- We know that multiple processes will be sharing the CPU
 - Possibly multiple threads in each process
 - Possibly multiple cores in the CPU
- Scheduling is creating a *policy* for sharing the CPU
 - Which process/thread is chosen to run, and when?
 - When (if ever) does the OS change which process is running?

Scheduling terminology

- Job - an execution unit handled by the scheduler (a.k.a. “task”)
 - Thread or process (doesn’t matter in this context)
 - Moves between Ready and Blocked queues
- Workload – set of jobs
 - Arrival time of each job
 - Run time of each job

When can the OS make scheduling decisions?

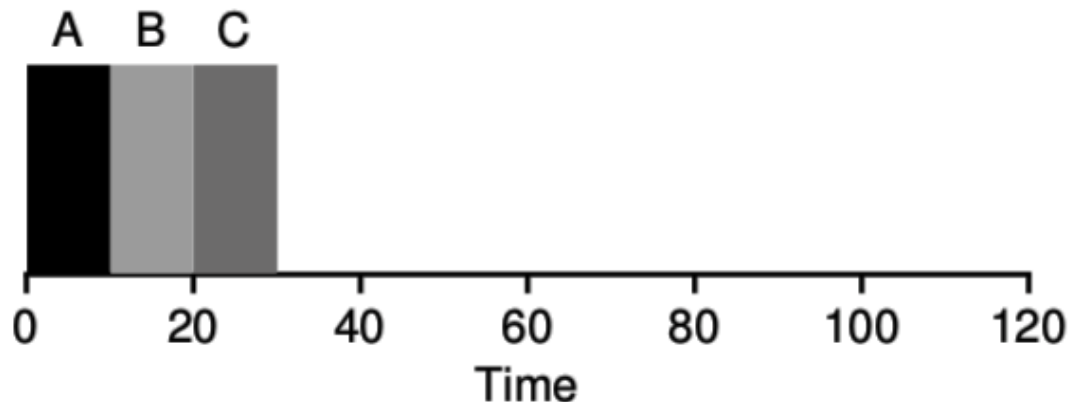
- Whenever the OS is actually running
 - i.e. after a context switch
- Possible triggers
 - System calls
 - Process/Thread creation/termination
 - I/O requests
 - Synchronization primitives (futex/condvar/semaphore)
 - Hardware events (interrupts)
 - I/O complete
 - Timer triggers

Goal of most schedulers: always have a job running

- The schedulers we look at in class are “work-conserving”
 - Always keeps scheduled resource busy if possible
 - When in doubt, make sure *some job* is running on the processor
 - Remember this for the lab and for exams!
- Counter-examples of “non-work-conserving” schedulers
 - Network I/O scheduling may rate-limit to avoid overloading network
 - Energy-limited systems may choose to run nothing to preserve energy

First scheduler: FIFO Scheduling

- First In, First Out (FIFO)
 - also known as First Come First Served (FCFS)
- Policy
 - First job to arrive gets scheduled first
 - Let a job continue until it is complete
 - Then schedule next remaining job with earliest arrival



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Metrics for systems

- Metric – standard for measuring something
 - Mathematical optimization: objective function
 - Economics: utility function
- For different computing scenarios, different metrics will be most important
 - Computing systems have different goals and uses
 - Performance metrics are often in conflict with each other
- Operating Systems are full of *tradeoffs*

A global scheduling metric

- Fairness
 - Each job should get a “fair” share of the processor
- Fair means different things of course
 - Could be “each job gets equal time”
 - Could be “each job starts in order it arrives”
 - Could be “each job is handled based on its priority”
- Scheduler should be fair with regards to the goals of the system it runs on

Other scheduling metrics

- Performance
 - How many jobs does the system complete?
 - How quickly are jobs completed?
- Responsiveness
 - How responsive does the system *feel* to users
- Energy use, types of jobs run, processor cores used, etc.

Different systems have different important metrics

- Example: network server
 - Request for home page
 - Request for contact page
- Example: personal computer
 - Text editor that the user is actively interacting with
 - Compilation running in the background
- Example: autonomous vehicle
 - Image recognition algorithms
 - Radio

Different systems have different important metrics

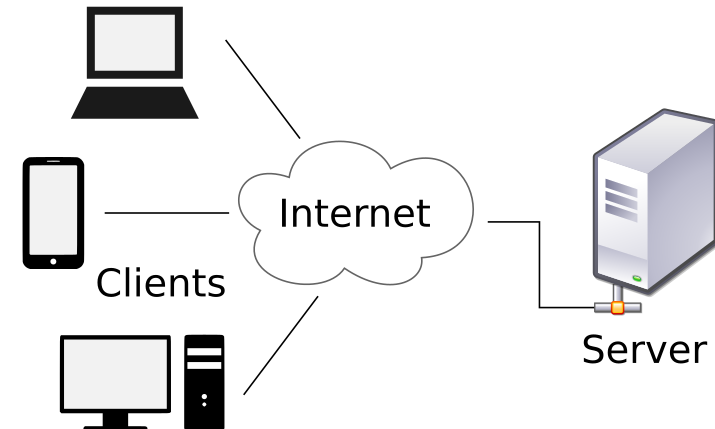
- Example: network server – **Batch System**
 - Request for home page
 - Request for contact page
- Example: personal computer – **Interactive System**
 - Text editor that the user is actively interacting with
 - Compilation running in the background
- Example: autonomous vehicle – **Real-time System**
 - Image recognition algorithms
 - Radio

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What are batch systems?

- Systems designed to run a set of provided tasks
 - No direct interaction with users
 - Predominantly run-to-completion jobs
- Example: banking systems or payroll management
- Modern example: network servers
 - Tasks are serving requests
 - Multiple types of requests, each with known runtimes

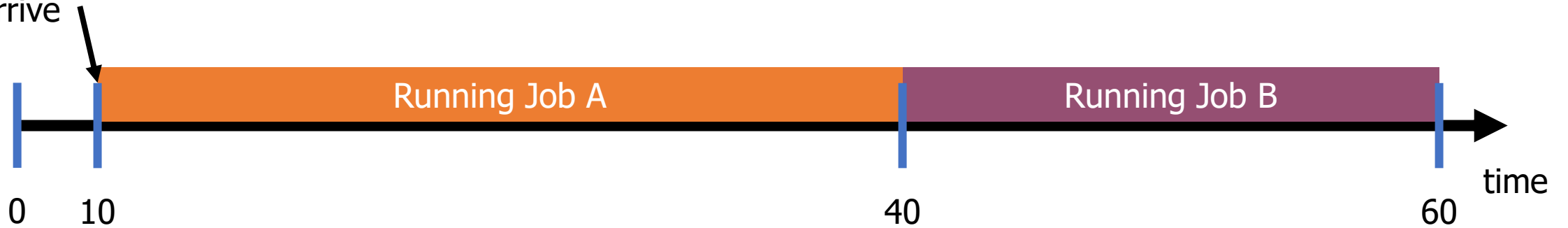


Metrics for batch systems

- Throughput
 - Jobs completed per unit time
 - $\text{Throughput} = \text{jobs_completed} / \text{total_duration}$
 - Higher is better
- Turnaround time
 - Duration from job arrival until job completion
 - $T_{\text{turnaround}} = T_{\text{completion}} - T_{\text{arrival}}$
 - Lower is better
 - Average turnaround time is computed across all jobs

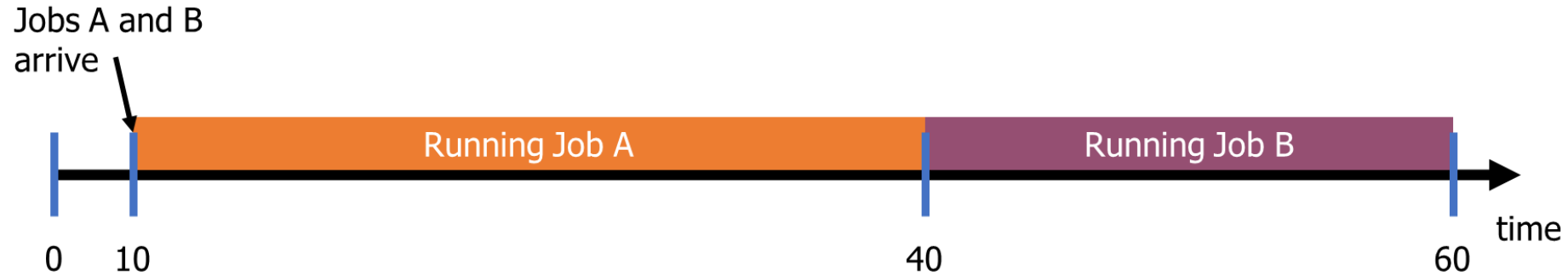
Example: throughput and turnaround

Jobs A and B
arrive



- Job A
 - Arrival: 10
 - Completion: 40
 - Duration: 30
- Job B
 - Arrival: 10
 - Completion: 60
 - Duration: 20

Example: throughput and turnaround



Throughput = jobs_completed / total_duration

$$T_{\text{turnaround}} = T_{\text{completion}} - T_{\text{arrival}}$$

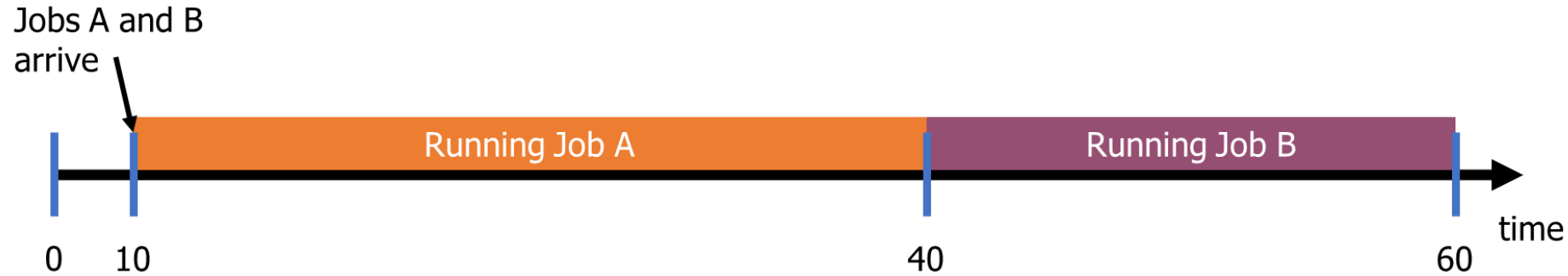
Throughput

Turnaround for A

Turnaround for B

Average Turnaround

Example: throughput and turnaround



$$\text{Throughput} = \text{jobs_completed} / \text{total_duration}$$

$$T_{\text{turnaround}} = T_{\text{completion}} - T_{\text{arrival}}$$

Throughput

$$2 \text{ jobs} / 50 \text{ time} = 0.04$$

Turnaround for A

$$40 - 10 = 30$$

Turnaround for B

$$60 - 10 = 50$$

Average Turnaround

$$(30 + 50) / 2 = 40$$

Batch scheduler metric

- Which metric is most relevant to a batch system scheduler with a finite list of processes?
 - Throughput or Turnaround
- Throughput only cares about sum of durations of jobs
 - Throughput is the same no matter whether A or B goes first
- Turnaround accounts for delays in scheduling a job
 - Swapping A and B would result in better average turnaround

Turnaround for A

$$60 - 10 = 50$$

Turnaround for B

$$30 - 10 = 20$$

Average Turnaround

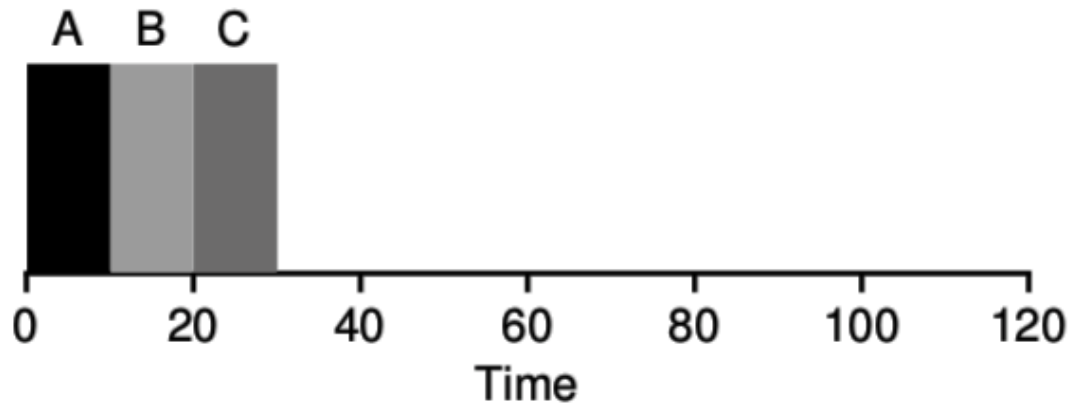
$$(50 + 20) / 2 = 35$$

Schedulers for batch systems

1. First In First Out
2. Shortest Job First
3. Preemptive Shortest Remaining Processing Time

1. FIFO Scheduling

- First In, First Out (FIFO)
 - assumption for now: all jobs arrive at time zero
- What is the average turnaround for this workload?
 - $(10 + 20 + 30)/3 = 20$

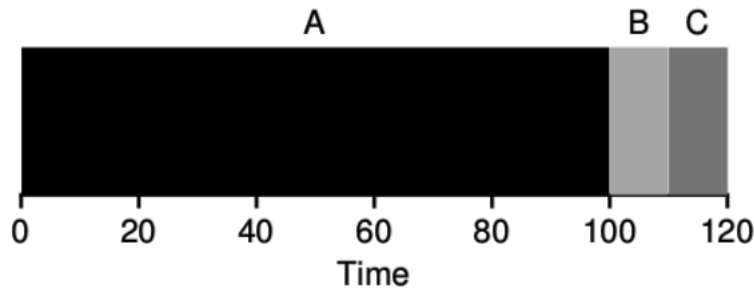


Check your understanding – FIFOs with different durations

- What is a problematic scenario for FIFO scheduling?
 - (consider job durations)

Check your understanding – FIFOs with different durations

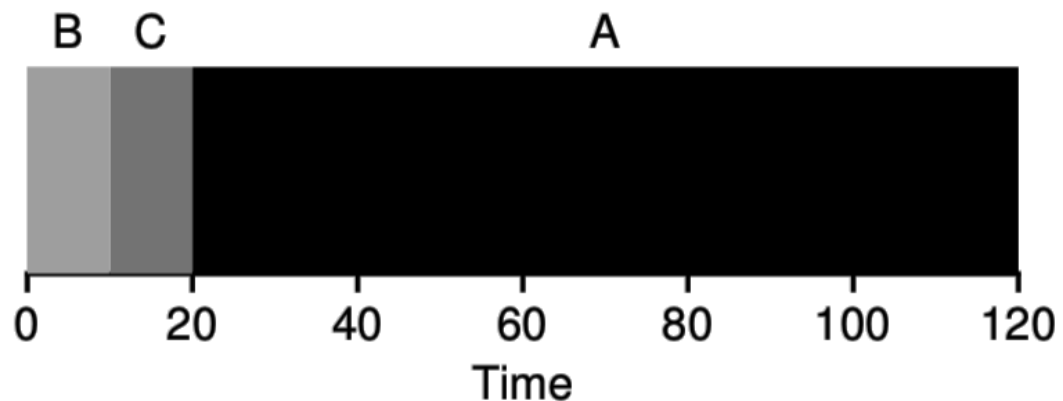
- What is a problematic scenario for FIFO scheduling?
- One big job can cause lots of jobs behind it to wait
 - Convoy effect – lots of small jobs stuck behind one big job



- Average turnaround time = $(100+110+120)/3 = 110$
 - Minimum average turnaround time = $(10+20+120)/3 = 50$

2. Shortest Job First

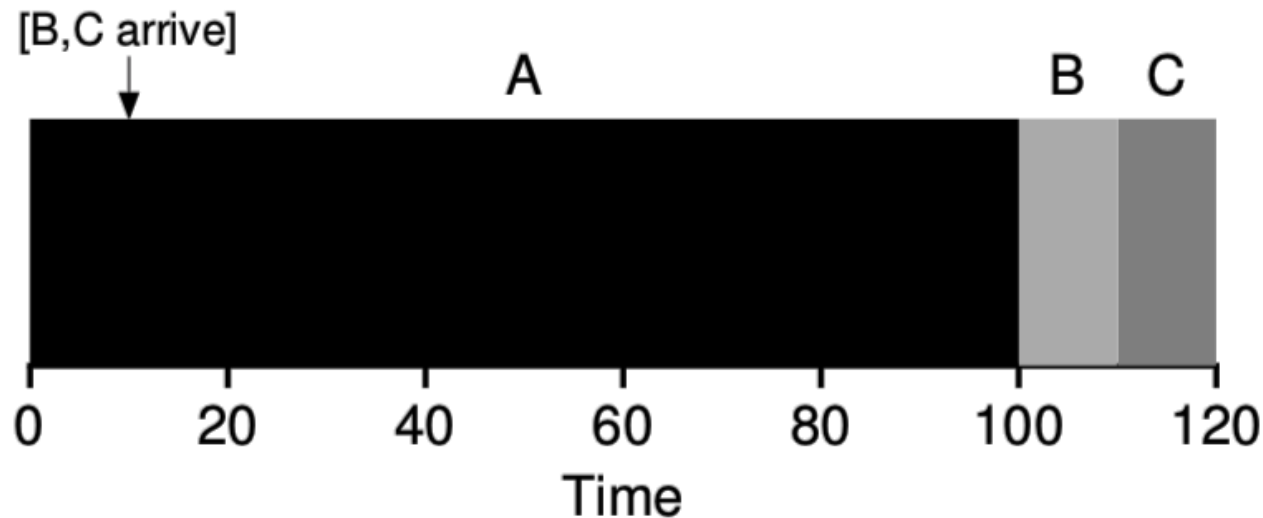
- Policy
 - Schedule the job with the smallest duration first
 - Let a job continue until it is complete
 - Then schedule next remaining job with smallest duration
- Essentially: complete a job as soon as possible
 - Minimizes the number of waiting jobs, minimizing average turnaround



Average Turnaround
 $(10+20+120)/3 = 50$

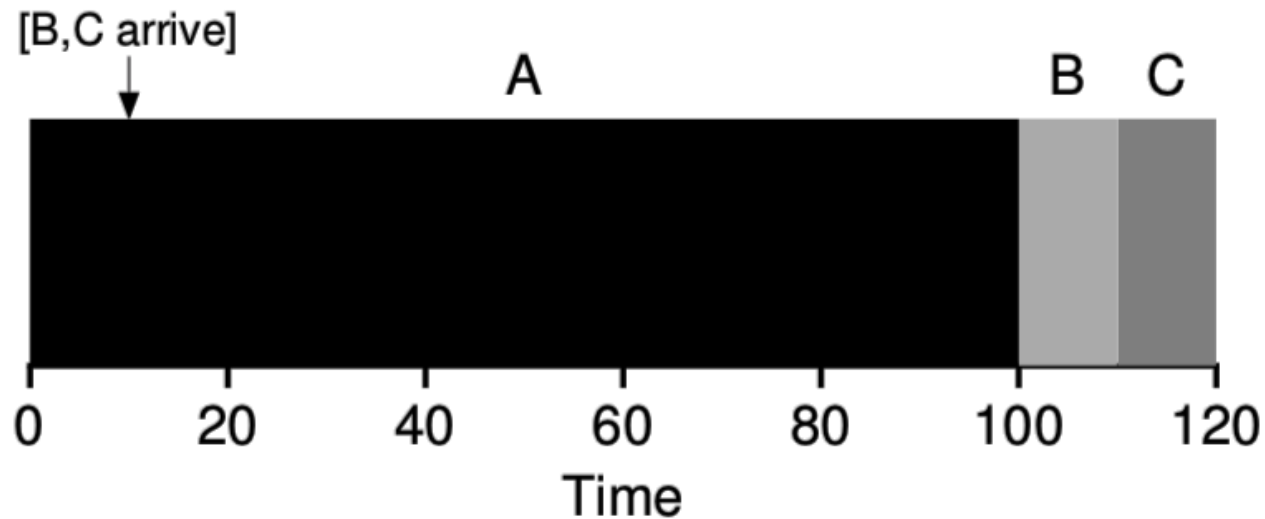
Shortest Job First can fail with late arrivals

- Scheduler's previously optimal decision could be invalidated by new job arrivals
 - If B and C arrive late, they will have to wait because A is already running



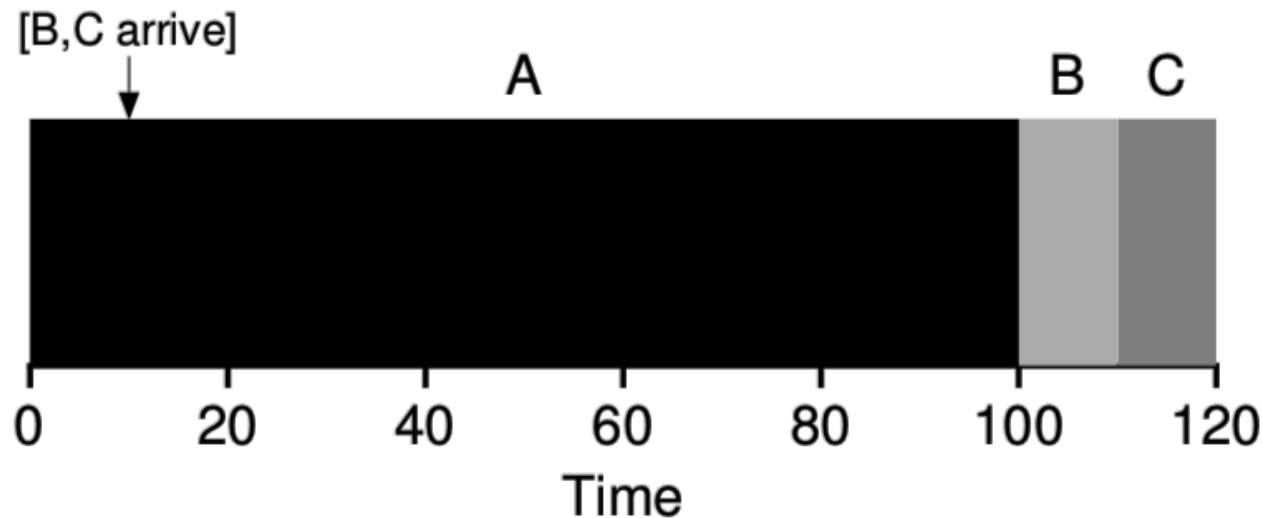
Check your understanding

- What is the average turnaround time for this example?
 - B and C arrive at time 10



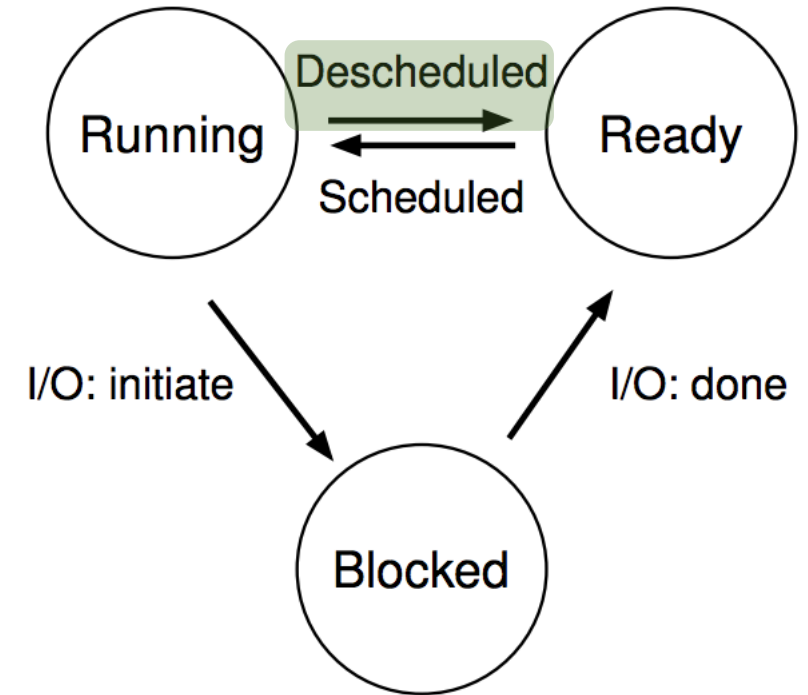
Check your understanding

- What is the average turnaround time for this example?
 - B and C arrive at time 10
- Average turnaround = $((100-0) + (110-10) + (120-10))/3 = 103.333333$



Preemption

- Let's add a new scheduler capability: preemption
- OS can "deschedule" jobs that are running
- This means it can make scheduling decisions more frequently
 - System calls
 - Interrupts
 - Timers



Context switching overhead

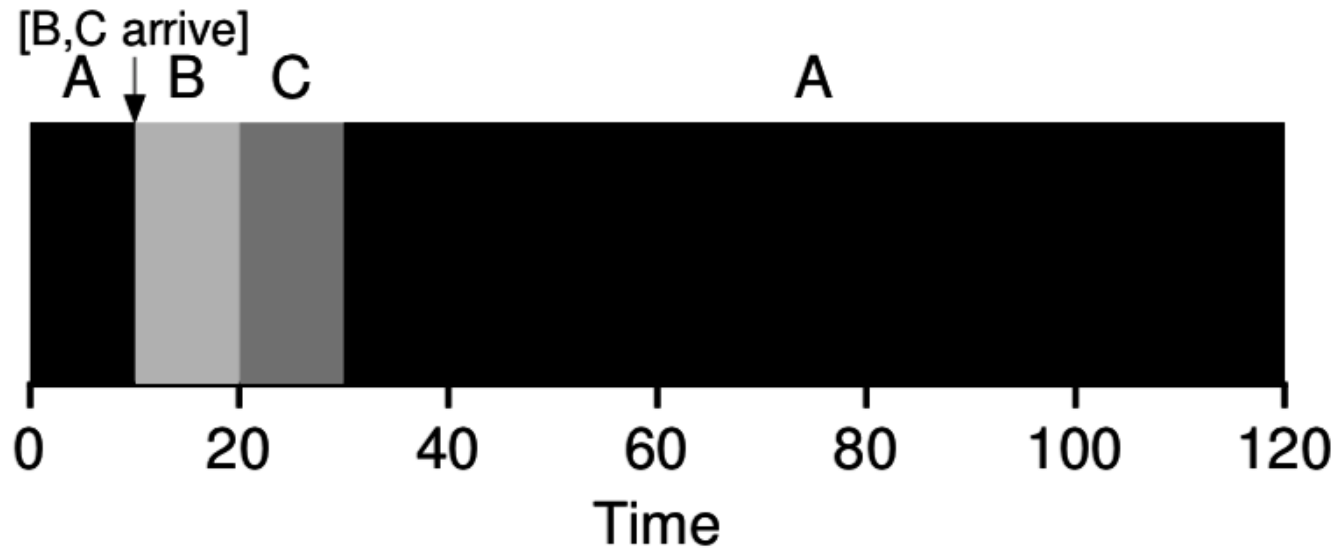
- Switching processes is expensive
 - Context switch to OS is on the order of 1 μ s (1 millionth of a second)
 - Switching registers and CPU mode
- Memory is often the larger expense though
 - New process has different physical memory pages
 - Which means that caches have to be cleared
 - Caches will “warm up” as the process runs
 - Less of a penalty to threads (only stack changes)
- Alternative option: cooperative scheduling through `yield()`

3. Preemptive Shortest Remaining Processing Time

- Also known as Shortest Time-to-Completion First
- Policy
 - Schedule job with smallest duration first
 - Preempt a running job when new jobs arrive
 - Then schedule job with smallest remaining duration
- Essentially, reevaluate schedule when new information is gained

Shortest Remaining Processing Time example

- A is preempted when B and C arrive at time 10
- Scheduler chooses B as new shortest remaining time
 - B=10, C=10, A=100



Average Turnaround
 $(120+10+20)/3 = 50$

Break + Starvation and scheduling

- Starvation can occur in schedulers
 - When one job will never actually get a chance to run
- We've discussed:
 - FIFO, Shortest Job First, and Shortest Remaining Processing Time
 - Which of these can exhibit starvation?

Break + Starvation and scheduling

- Starvation can occur in schedulers
 - When one job will never actually get a chance to run
- We've discussed:
 - FIFO, Shortest Job First, and Shortest Remaining Processing Time
 - Which of these can exhibit starvation?
 - Shortest Remaining Processing Time
 - Shortest Job First too if we allow new job arrivals (without preemption)
 - Arriving short tasks could lead a long task to never be scheduled

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What are interactive systems?

- Every computer you directly interact with
 - Desktops, laptops, smartphones
- Differences from batch systems
 - Humans are “in-the-loop”
 - Computer needs to feel responsive for programs they are using
 - **Many jobs have no predefined duration**
 - How long does Chrome run for?
- Still have some batch jobs though (background services)

Metric for interactive systems

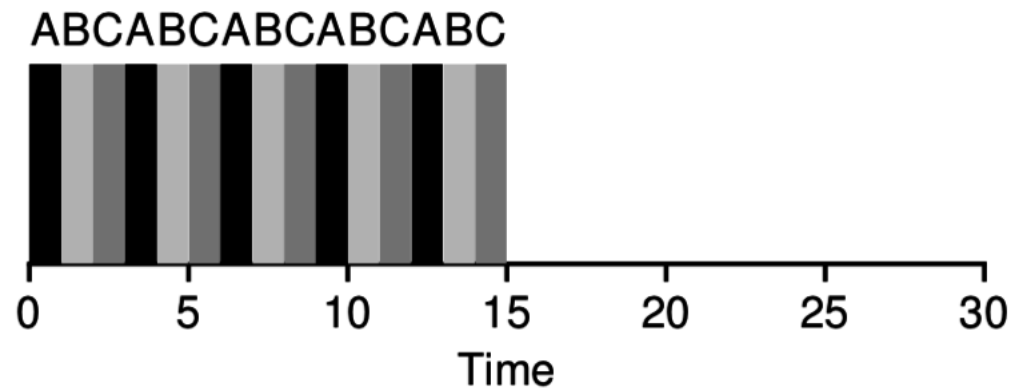
- Response time
 - Time from arrival until the job **begins** execution
 - Doesn't matter how long the job takes to run since it runs indefinitely
 - $T_{\text{response}} = T_{\text{start}} - T_{\text{arrival}}$
- Particularly useful for interactive processes
 - Need to quickly show that they are reacting to user inputs
 - Exact total run duration isn't so important though

Schedulers for interactive systems

1. Round Robin
2. Multi-Level Feedback Queue

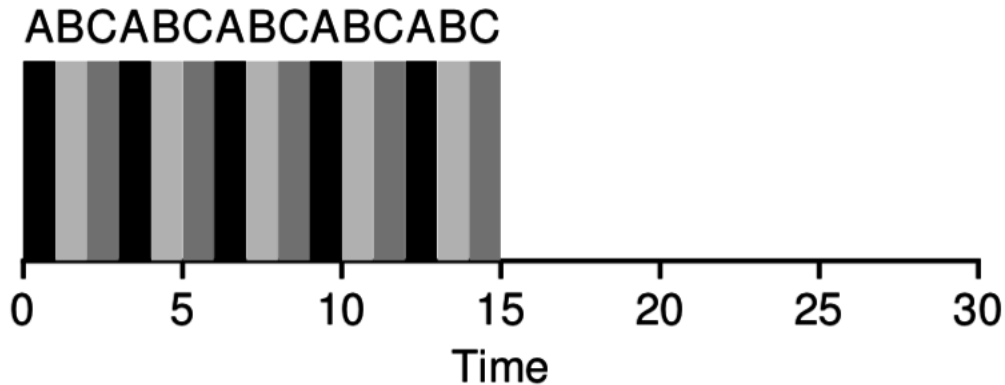
1. Round Robin

- Round Robin scheduling runs a job for a small *timeslice* (quanta), then schedules the next job



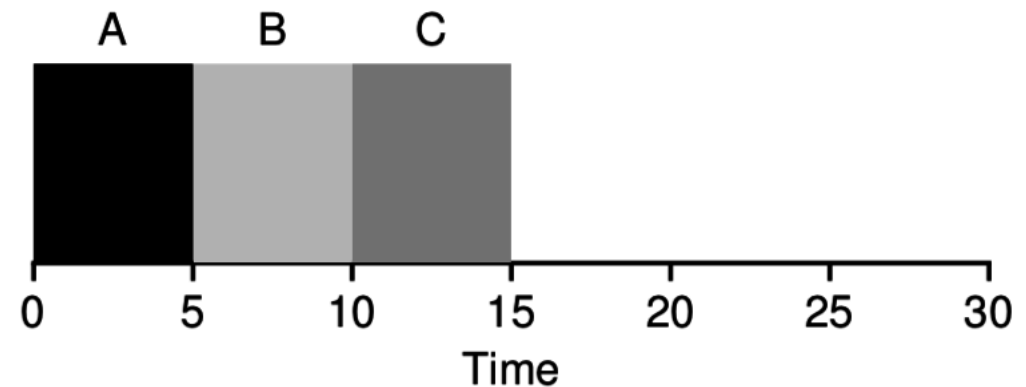
- If all jobs arrive at time 0
 - Average response time = $(0 + 1 + 2)/3 = 1$
- Smaller timeslice means smaller response time

Different policies favor different metrics



Round Robin scheduling:

- Avg turnaround time = **14**
- Avg response time = **1**

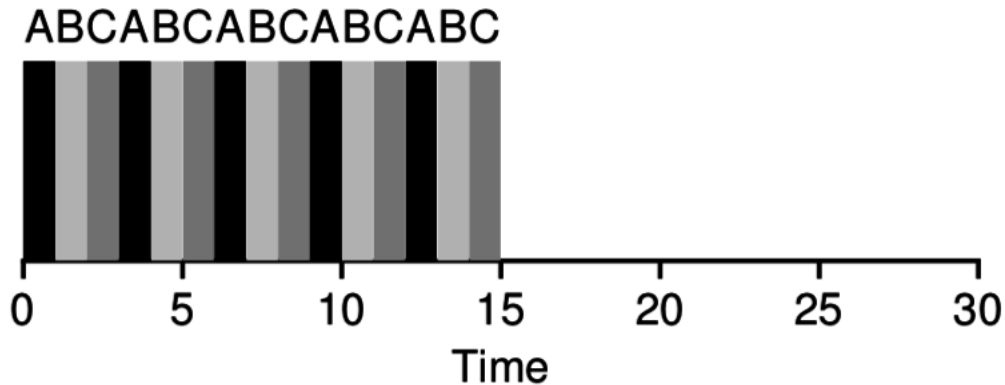


Shortest Job first or **SRPT**:

- Avg turnaround time = **10**
- Avg response time = **5**

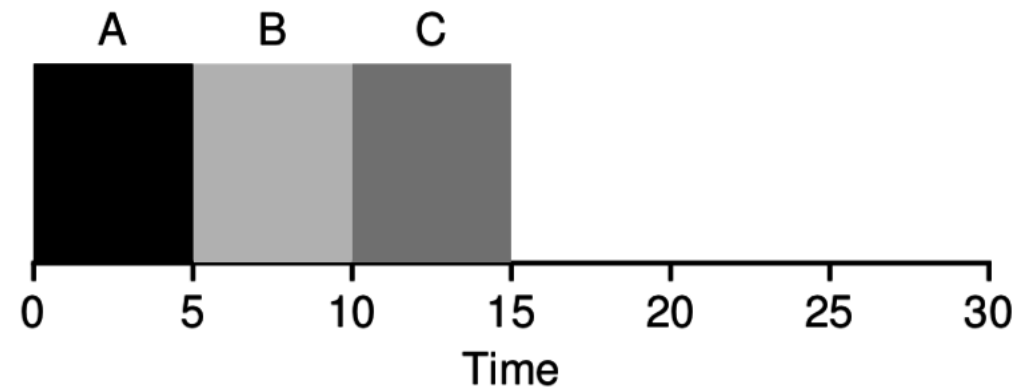
Better response time versus Better turnaround time

Remember, context switches are not free



Round Robin scheduling:

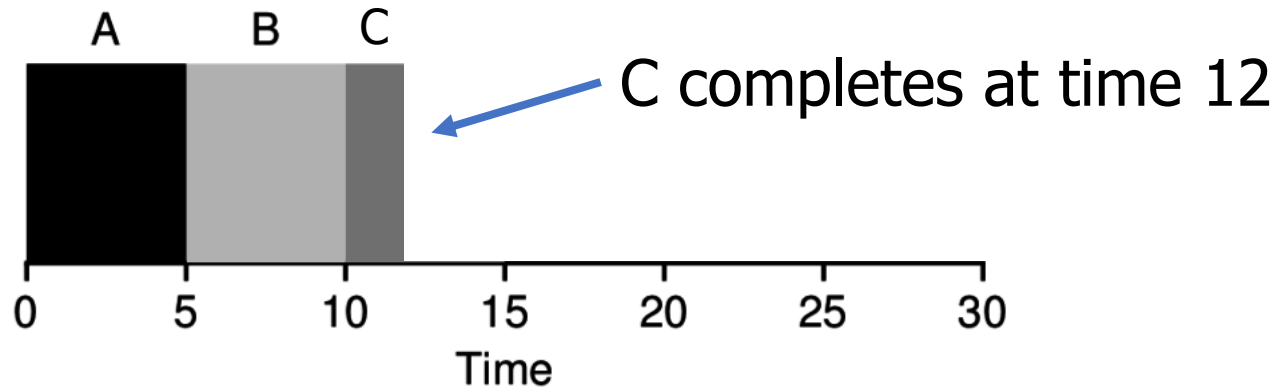
- Context switches = **14**
- In a real OS, Round Robin would take an extra $\sim 12 \mu\text{s}$
 - Plus more time lost with cold caches...
- Timeslice must be **much** greater than context switch time
 - Usually timeslice is $\sim 1 \text{ ms}$ and context switch is $\sim 1 \mu\text{s}$



Shortest Job first or *SRPT*:

- Context switches = **2**

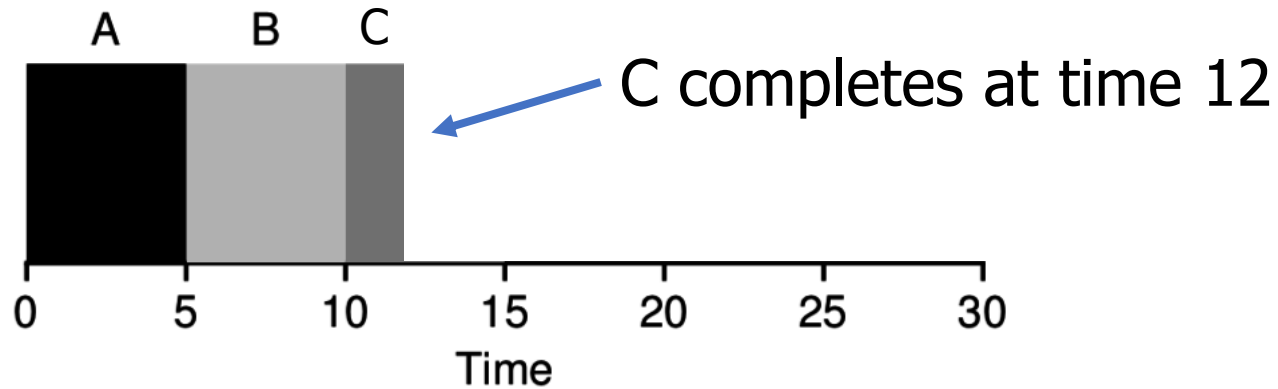
Handling a round-robin edge case



Assume quantum
(timeslice duration)
is 5

- What should the scheduler do?
 1. Schedule nothing for the rest of the timeslice
 2. Schedule a new job for the rest of the timeslice
 3. Schedule a new job with a new, full timeslice

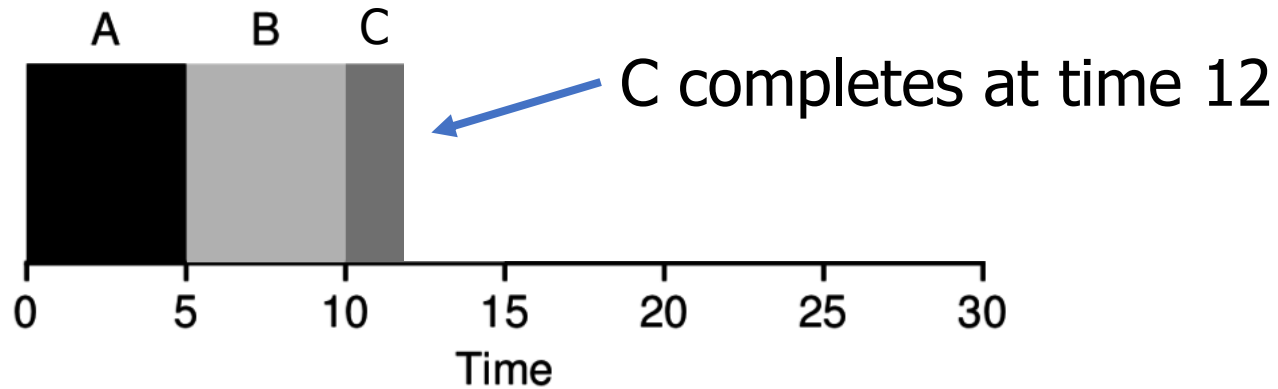
Handling a round-robin edge case



Assume quantum
(timeslice duration)
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- What should the scheduler do?
 - ~~1. Schedule nothing for the rest of the timeslice~~ **Not work-conserving**
 2. Schedule a new job for the rest of the timeslice
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Handling a round-robin edge case



Assume quantum
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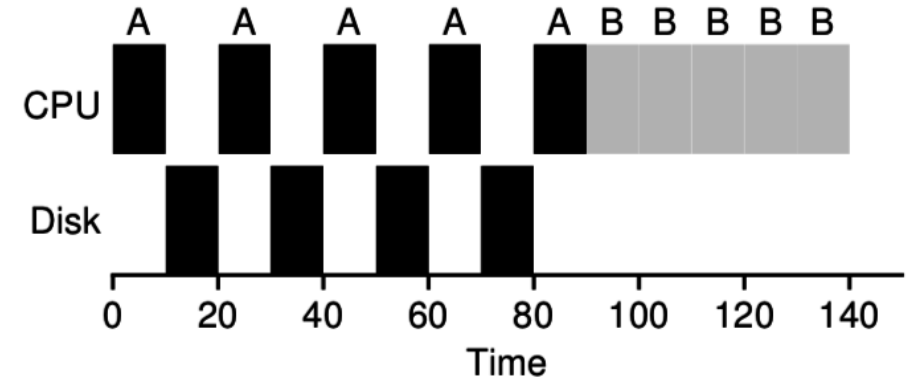
- What should the scheduler do?
 - ~~1. Schedule nothing for the rest of the timeslice Not work-conserving~~
 - ~~2. Schedule a new job for the rest of the timeslice **Not fair**~~
 3. Schedule a new job with a new, full timeslice **Correct!**

Timeslices are attached to jobs

- Each *job* gets its own timeslice duration
- Jobs may use less than their entire timeslice voluntarily
 - They could complete
 - They could become blocked
 - They could decide to yield
- The scheduler, however, should always provide a full timeslice
 - In previous example: runtime of one job shouldn't affect another job

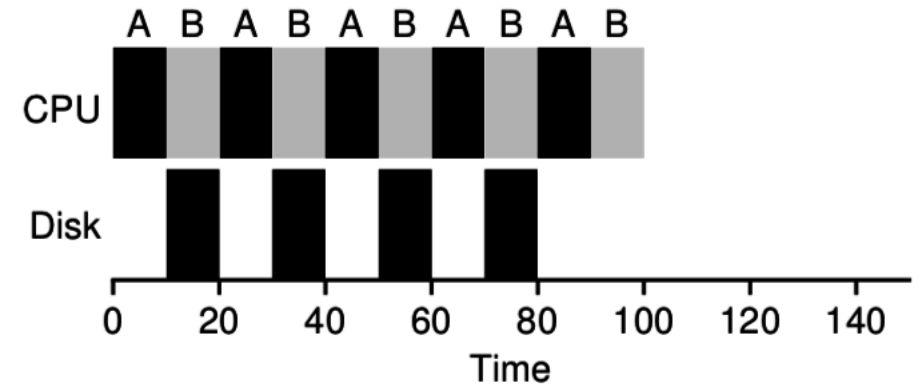
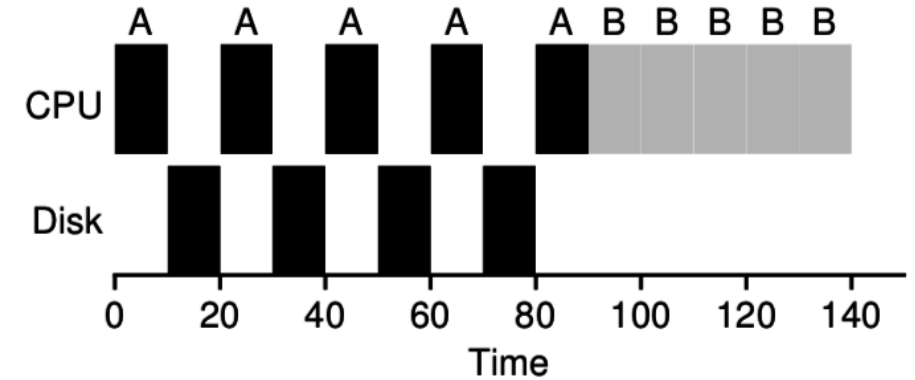
I/O creates scheduling ***overlap*** opportunities

- Job A does I/O every ten milliseconds and each I/O takes 10 ms:
- A is **blocked** during its I/O.
 - It's just waiting for data from the disk
 - But it does not need the CPU



I/O creates scheduling ***overlap*** opportunities

- Job A does I/O every ten milliseconds and each I/O takes 10 ms:
- A is **blocked** during its I/O.
 - It's just waiting for data from the disk
 - But it does not need the CPU
- We can schedule another job during process A's I/O
 - Once a job is blocked, the scheduler can immediately move to the next job!



Jobs can be I/O-bound or CPU-bound

- CPU-bound process
 - Lots of computation between each I/O request
 - Actually needs to do computation on a processor
 - Example: doing matrix math
- I/O-bound process
 - Very little computation between each I/O request
 - Just needs a processor to figure out its next I/O request
 - Example: searching a file system for a file name

Scheduling goal: I/O-bound before CPU-bound

- First maximize I/O
 - Run the I/O-bound jobs as quickly as possible,
 - So they can send next I/O request,
 - And our disks, network cards, etc. are maximally used
- Then fill up the processor(s)
 - Lots of room for multiprogramming between the I/O requests
 - Blocked jobs are still “progressing” as their I/O is fetched

Scheduling goal: I/O-bound before CPU-bound

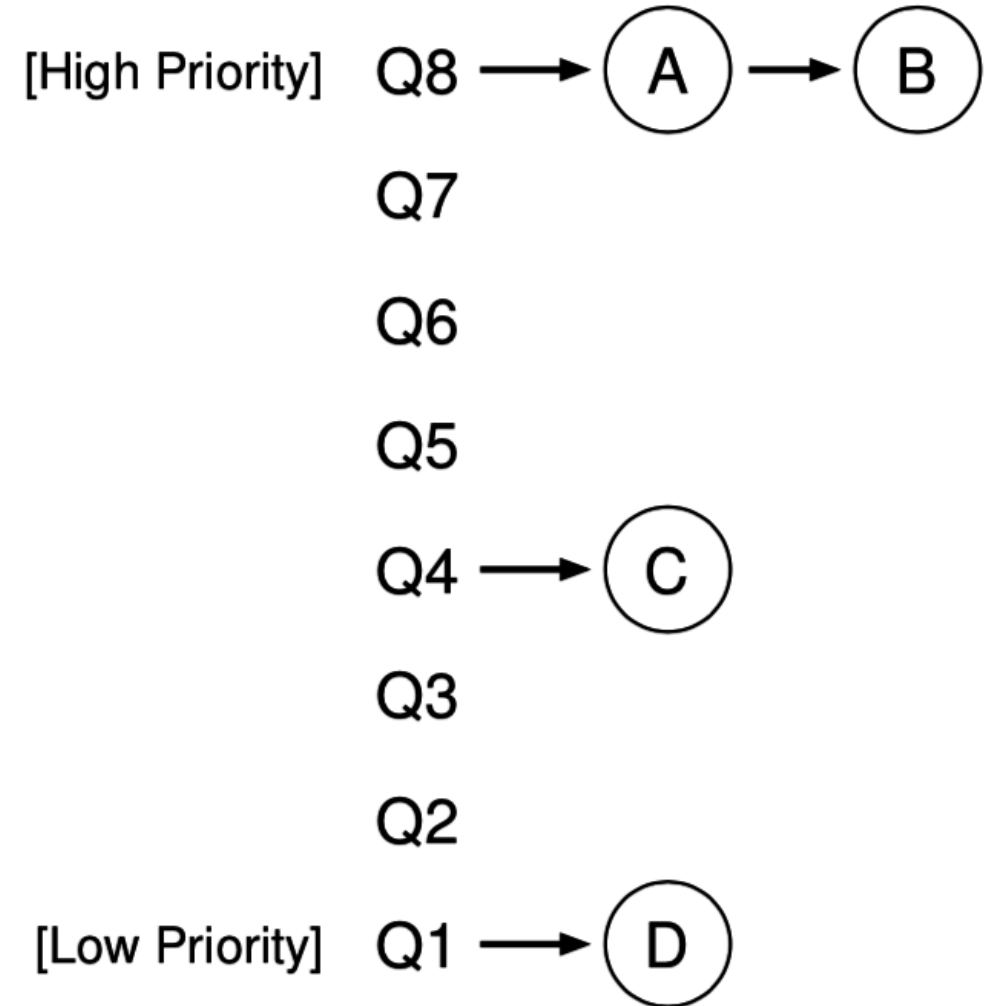
- First maximize I/O
 - Run the I/O-bound jobs as quickly as possible,
 - So they can send next I/O request,
 - And our disks, network cards, etc. are maximally used
- Then fill up the processor(s)
 - Lots of room for multiprogramming between the I/O requests
 - Blocked jobs are still “progressing” as their I/O is fetched
- But how do you know when a job is going to use I/O?
 - Can't know the future
 - Can track past behavior of the job

2. Multi-Level Feedback Queue (MLFQ)

- General purpose scheduler to support multiple goals
 - Good response time for interactive jobs
 - Good turnaround time for batch jobs
 - Achieves this by prioritizing I/O bound jobs over CPU bound jobs
- Policy
 - Automatically attach priority to jobs:
 - Interactive, I/O bound jobs should be highest priority
 - CPU bound, batch jobs should be lowest priority
 - Apply different round robin timeslices to each priority level

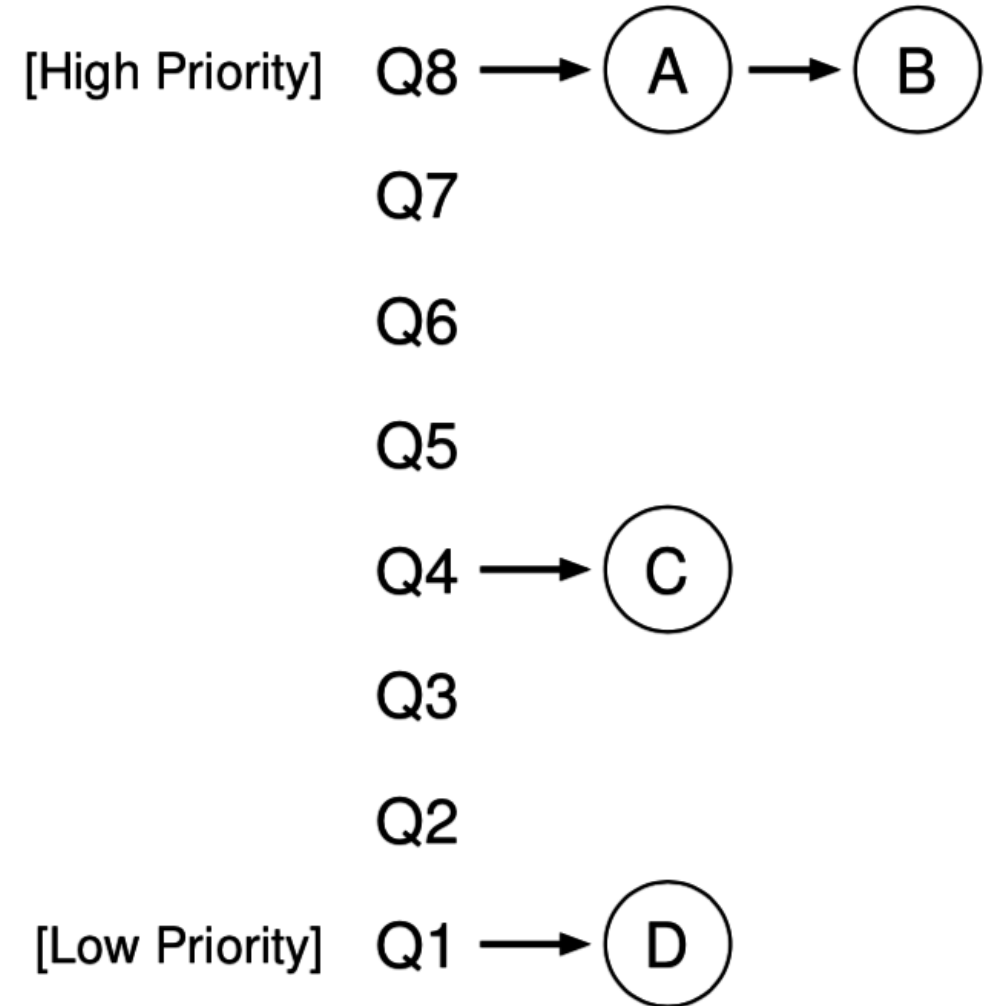
Multi-Level Feedback Queue Details

- Run highest priority level available
 - Round robin among jobs there
- When all jobs at a level are blocked on I/O
 - Move down to next lower level
- Long running jobs lose priority
 - Set a processor usage limit at a given level
 - When used up, demote job one level

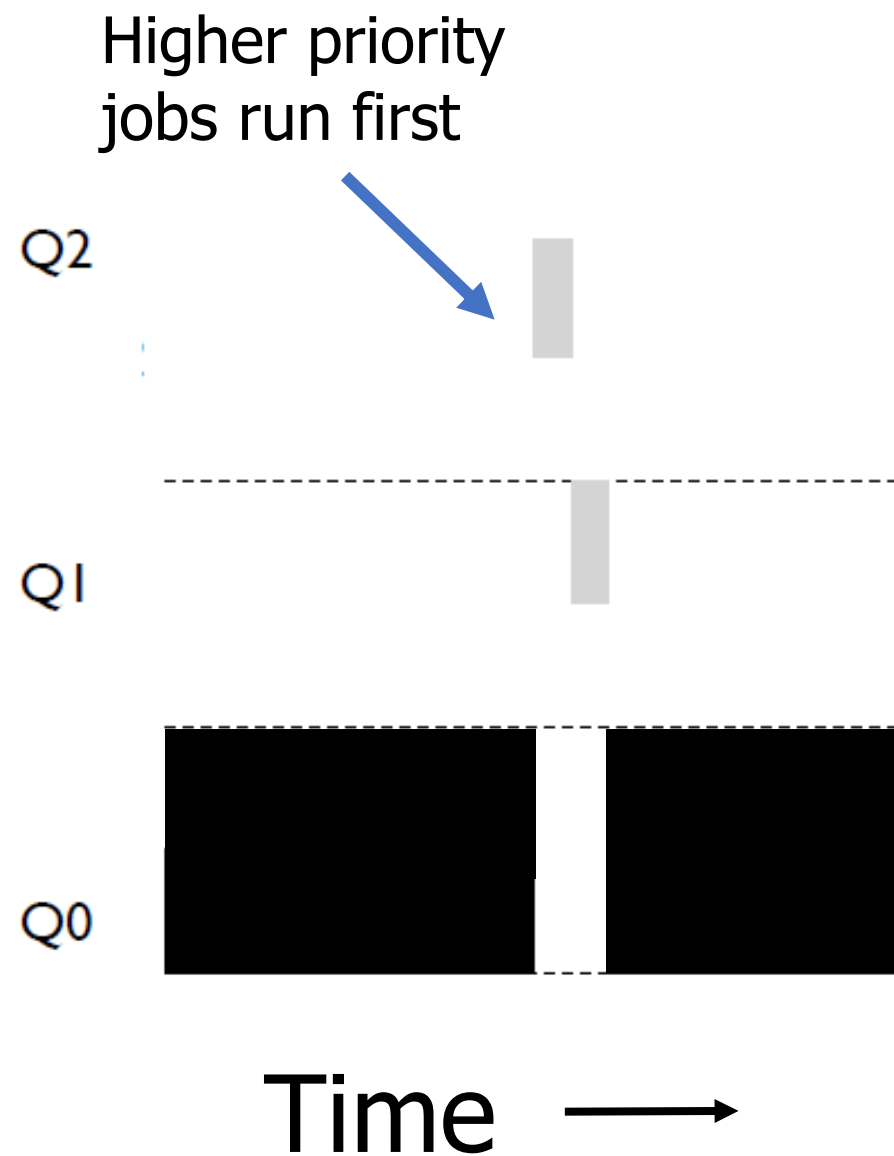
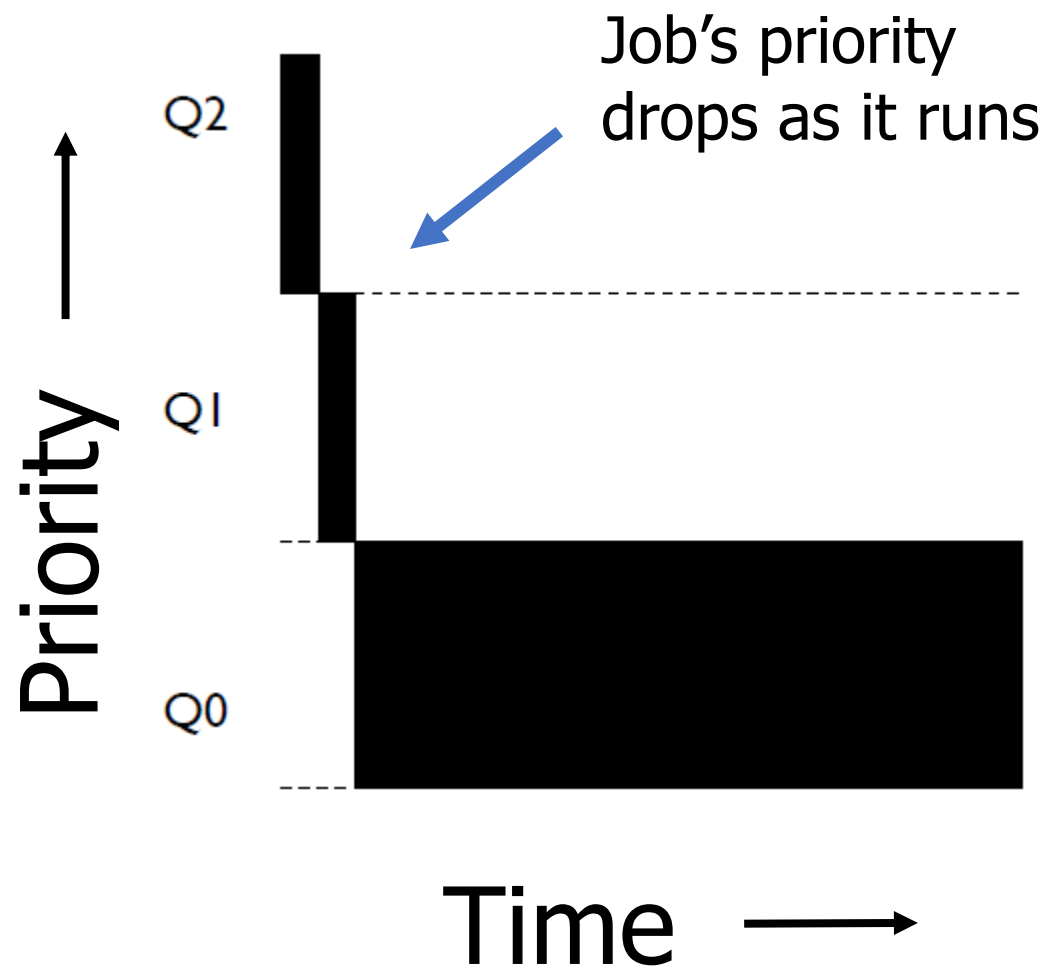


MLFQ Rules

1. If $\text{Priority}(\mathbf{J}_1) > \text{Priority}(\mathbf{J}_2)$, \mathbf{J}_1 runs
2. If $\text{Priority}(\mathbf{J}_1) = \text{Priority}(\mathbf{J}_2)$, \mathbf{J}_1 and \mathbf{J}_2 run in Round Robin
3. Jobs start at top priority
4. When a job uses its time quota for a level, demote it one level
5. Every **S** seconds, reset priority of all jobs to top

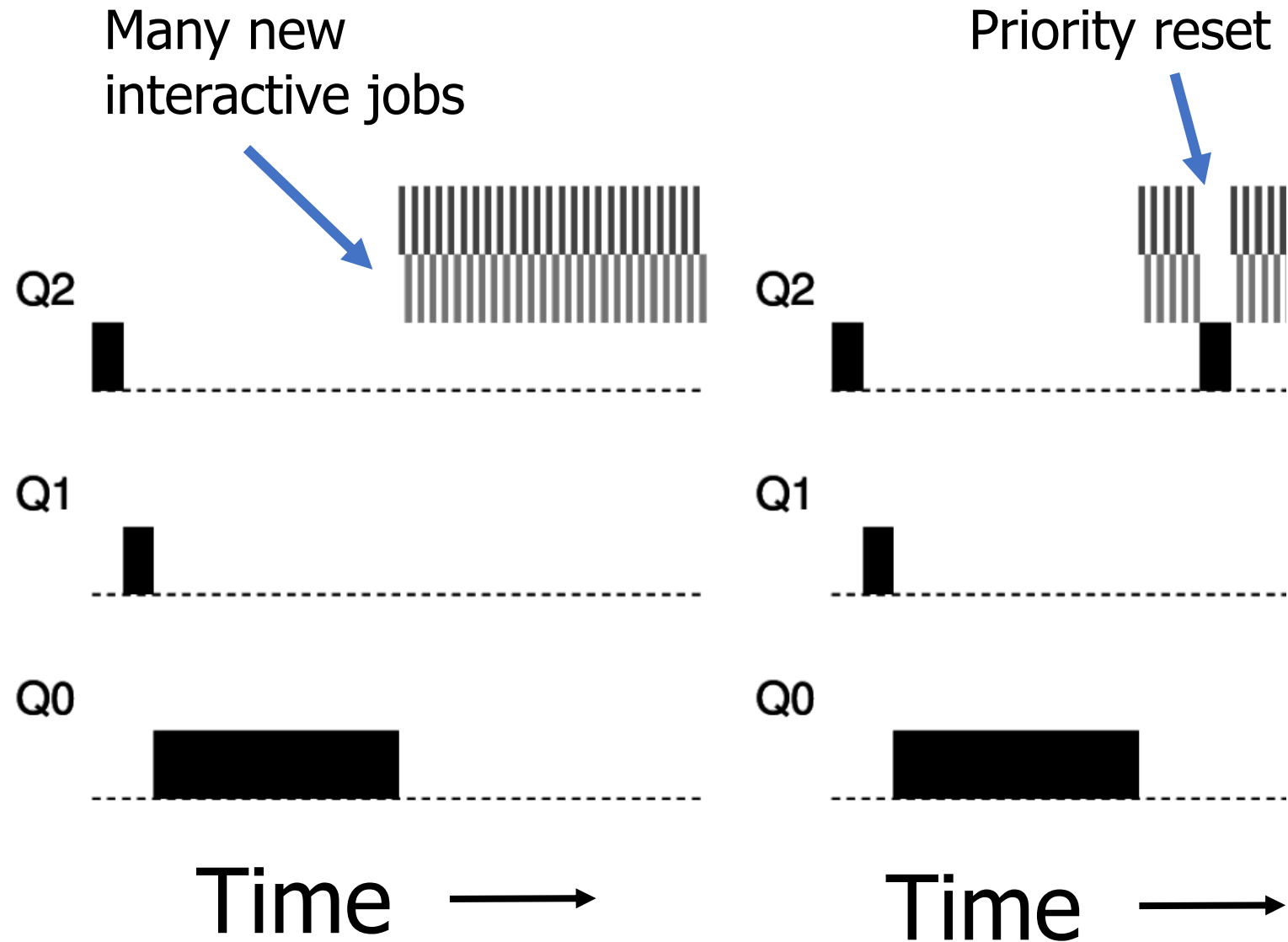


MLFQ Example



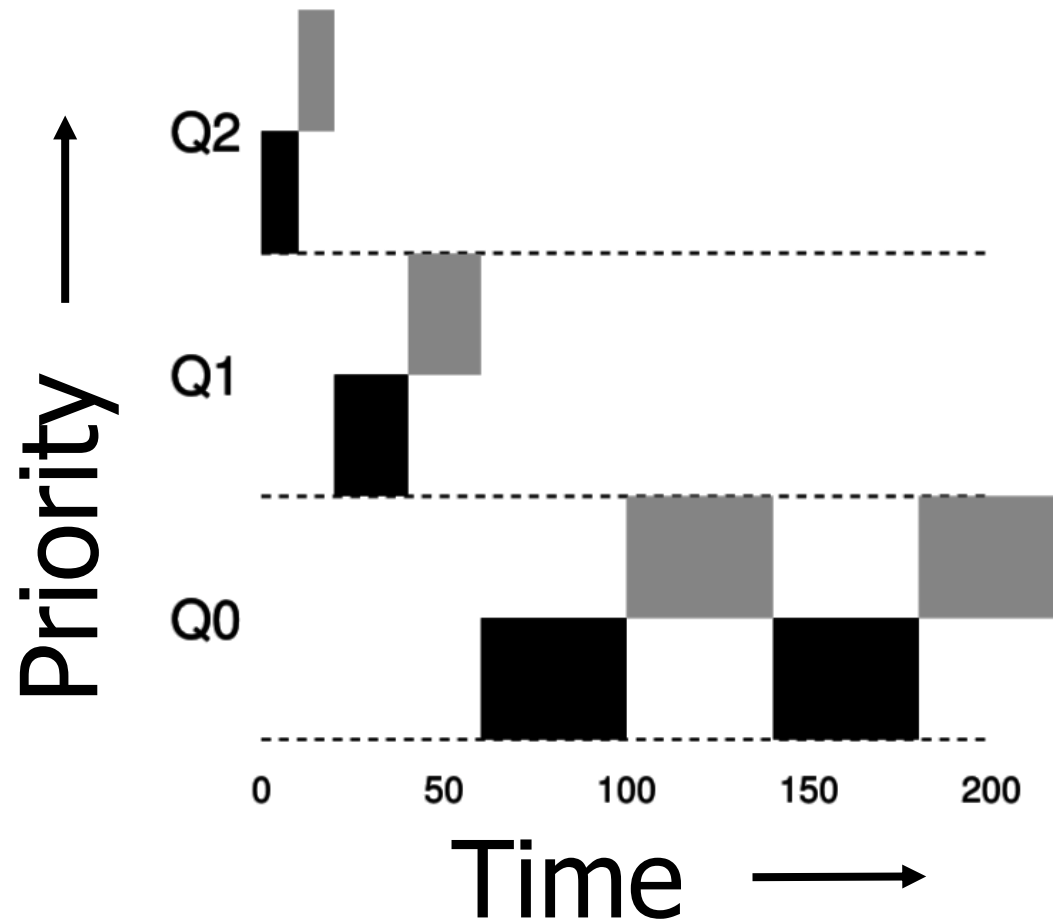
MLFQ avoids starvation with periodic priority reset

- Low priority jobs could starve if there are enough interactive jobs
- MLFQ avoids starvation by periodically resetting priorities



Change timeslices to optimize response and turnaround

- Lower priority jobs are CPU bound, not interactive
 - So we can use longer timeslices to minimize context switches



MLFQ parameters

- Every MLFQ implementation needs to choose a bunch of parameters
 - How many queues/priority levels?
 - When does a job get demoted in priority?
 - How often to reset priority for everything?
 - How large is the timeslice at each priority level?

MLFQ in the wild

- The embedded OS I work on has an MLFQ scheduler!
 - <https://github.com/tock/tock/blob/master/kernel/src/scheduler/mlfq.rs>
- How many queues/priority levels?
 - Three
- When does a job get demoted in priority?
 - If it ever uses its whole timeslice without blocking
- How often to reset priority for everything?
 - Every five seconds
- How large is the timeslice at each priority level?
 - 10 ms, 20 ms, 50 ms

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