Lecture 17 Energy Management

CE346 – Microprocessor System Design Branden Ghena – Spring 2021

Some slides borrowed from: Josiah Hester (Northwestern), Prabal Dutta (UC Berkeley), Brandon Lucia (Carnegie Mellon)

Northwestern

Administrivia

- Quiz 4 is available
 - Due Friday
- Demo details coming on Wednesday

• ~9 days to complete your project

Today's Goals

- Consider energy and microcontroller systems
 - What are the energy sources?
 - What are the energy sinks?
- Understand sleep mode on a microcontroller
- Discuss software for low-energy operation

Outline

• Energy Sources

- Energy Management
 - Sleep
 - Intermittent computing

Energy sources

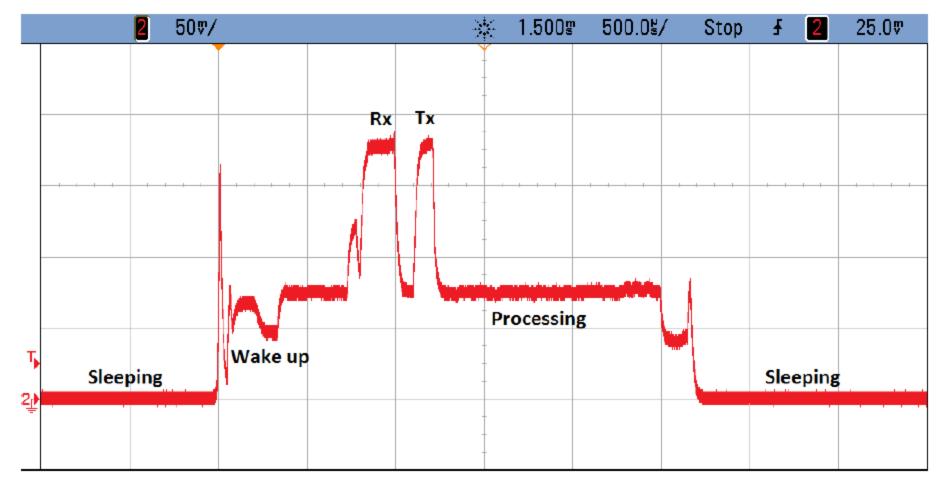
• Need some way to gain energy to power system

- Choices affect mobility, lifetime, software design, and capabilities
 - Is the device tied to its power source?
 - Must a human manually provide more energy?
 - How do I write software to ensure "progress" is made?
 - What sensors/actuators can the device run?

Measuring energy use

- Base equations
 - Power = Current * Voltage (Watts)
 - Energy = Power * Time (Joules)
- Energy = volts * amps * seconds
 - Voltage is *usually* constant for a system
 - Time is how long you are running for / measurement period
 - Current changes based on activities being done
 - Often energy is presented as a current draw
 - Maybe an average current draw
 - With Voltage and Time implicit

Example current trace during wireless communication



Current Consumption versus Time during a single Connection Event

Wired power through USB

- Provides 5v at up to 500 mA (USB 2.0) or 900 mA (USB 3.0)
 - Or power delivery specifications, which can do far more power
- Must be converted to different voltage to use
 - Voltage regulator takes in 5v and spits out 3.3v
 - Has its own maximum current!
- System is limited by the minimum of USB or regulator power
 - Microbit: regulator gives 3.3v at up to 600 mA
 - USB 2.5 Watts, Regulator 1.98 Watts ⇒ System 1.98 Watts
 - This is a max! Stay 15-30% below regulator limit

Thinking about energy

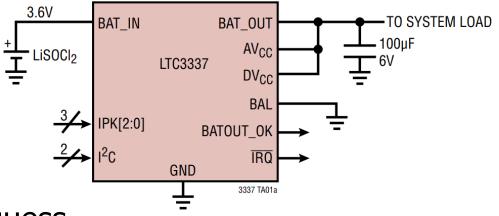
- Batteries often list energy in mA*h (milliamp hours)
 - Coin cell battery: 3v at 220 mAh
 - 2x AA battery: 3v at 2000 mAh
 - iPhone 11 battery: 3.7v at 3000 mAh
- Also usually limited by regulator
 - Sometimes just directly connected to system
 - We can run at 3v just fine! (3.7v is no good though)
- Voltage can vary with charge
 - But only a little, right before battery is depleted
 - Example: coin cell goes down to ~2.7 volts





How are batteries measured?

- Measuring energy remaining is a difficult problem
 - Many questions to be handled
 - How much did it start with?
 - How much energy has been used?
 - What type of battery is it?
 - Energy is not as constant a quantity as one would hope
 - Pulling out lots at once has an overhead penalty
- Coulomb Counter (aka Battery Fuel Gauge)
 - Designed for a specific battery "chemistry"
 - Monitors charge flowing in each direction
 - I2C interface for reading battery state
- Accuracy is not exact, more of an educated guess



How are batteries managed?

- Usually a dedicated IC for charging and managing battery packs
 - Recharges battery with appropriate amount of current
 - Monitors issues of battery health
 - Various status monitoring
 - Overcharge, undercharge
 - Overcurrent
 - Overtemperature, undertemperature
 - Will go so far as to cut off the system to protect the battery
- Takeaway: complicated problem, approach with caution!
 - Best to reuse an existing design, if possible

Microbit only uses battery energy in a simple way

- Battery input connects directly to regulator
 - No protection for battery health
 - No battery charging capabilities
- Usually this is fine for simple, low-power systems

Energy harvesting

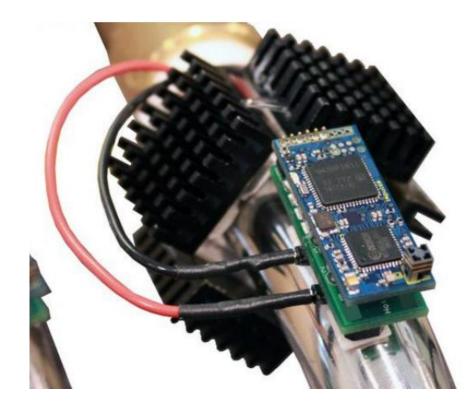
- Grab energy from the environment and use that!
 - Could augment with a battery and use energy to recharge
 - Could go entirely batteryless and live on harvested energy alone

Sources

- Light (outdoor or indoor. most successful)
- Airflow (outdoor or air vents)
- Motion (on human body)
- Temperature differential (difficult in practice)
- RF (very low energy source)

Temperature harvesting from hot pipes

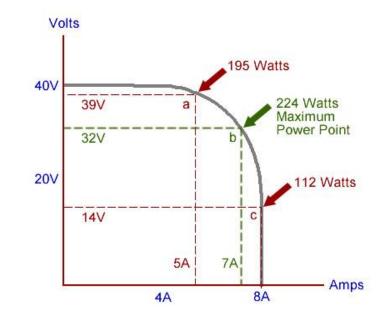
- Peltier junctions create a voltage from temperature differential
 - Challenge: needs a large differential for more energy





Managing harvested energy

- Often uses an IC to pull in energy and provide to system
- Harvested voltage/current are often very small
 - Signal in millivolts is pretty common
 - Need to accumulate over time to power system
 - Fill up a capacitor
- Need particular load for maximum power
 - ICs often implement Maximum Power Point Tracking (MPPT)
 - Varies load automatically to always harvest the most possible energy



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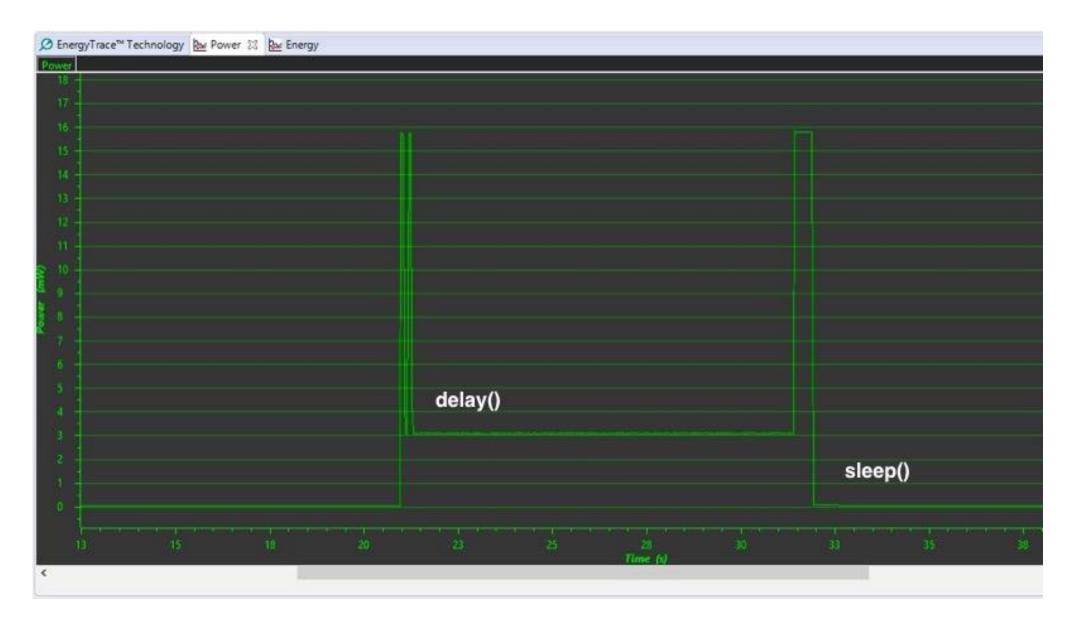
Thinking about energy

- Battery energy
 - Coin cell battery: 3v at 220 mAh
 - 2x AA battery: 3v at 2000 mAh
 - iPhone 11 battery: 3.7v at 3000 mAh
- nRF52833 active current: 5.6 mA (at 3v)
 - Coin cell: 40 hours -> ~2 days
 - 2x AA: 360 hours -> ~15 days
 - iPhone 11: 535 hours -> ~22 days
- So how does any of this work???





Sleep mode power draw



Microcontroller sleep modes

- Sleep mode
 - Processor stops running
 - Most peripherals are disabled
 - Continues until an interrupt occurs and wakes the microcontroller
 - Usually a timer or GPIO input
- nRF52833 sleep mode current: 1.8 µA (GPIO port event only)
 - Coin cell: 122222 hours -> ~5000 days -> ~14 years
- Low-power systems shoot for less than 1% duty cycle
 - Average current of ${\sim}100~\mu\text{A}$ or less
 - Warning: other stuff on the board counts!!
 - LEDs are 1-10 mA each... Power is not a concern of the Microbit

Microbit current draw (microcontroller)

- Active CPU
 - 5.6 mA (executing from Flash)
 - 1.8 μ A (sleep mode with RAM retention)
- Transmitting RF packet
 - 15.5 mA (+8 dBm)
- Other peripherals
 - SAADC: 1.37 mA
 - Timer: 729 µA (for any Timer peripheral)
 - I2C: 6.6 mA (pull-down resistors when transmitting 0 bit)
 - Everything else is handfuls of μA

Microbit current draw (non-microcontroller)

- KL27 (JTAG interface microcontroller)
 - 2 µA sleep, 8 mA active
- Speaker
 - 0-27.5 mA (changes with input signal)
- Microphone
 - 0-120 μ A (activated with GPIO pin)
- Accelerometer/Magnetometer
 - 2-212 μ A (depends on sensing rates, 200 is magnetometer)
- LEDs
 - 0-230 mA (can be activated individually)
- Everything else
 - 0-1 mA (mostly due to pull-up resistors)

Max and min current for Microbit

- Maximum current: 280 mA at 3.3 volts (~1 W)
 - With *everything* active
 - Well within limits of regulator
- Minimum current
 - \sim 15 mA (always-on power LED)
 - If you removed the power LED:
 - <100 μ A (with everything off)

nRF52 sleep mode

- Triggered with assembly instruction
 - WFI (Wait For Interrupt) or WFE (Wait For Event)
- Stops processor until woken by interrupt, exception, or event
- On nRF52 automatically disables high frequency clock if unneeded

Software stops when the processor does, but peripherals continue

• Problem: when the processor is off, no code is running

- Solutions
 - Peripherals can wake it up again
 - Can probably go for milliseconds to minutes without any actions
 - Timer interrupt can wake processor to do things
 - Have hardware handle some parts in the background without the processor's involvement
 - DMA
 - PPI

Controlling peripherals while processor sleeps

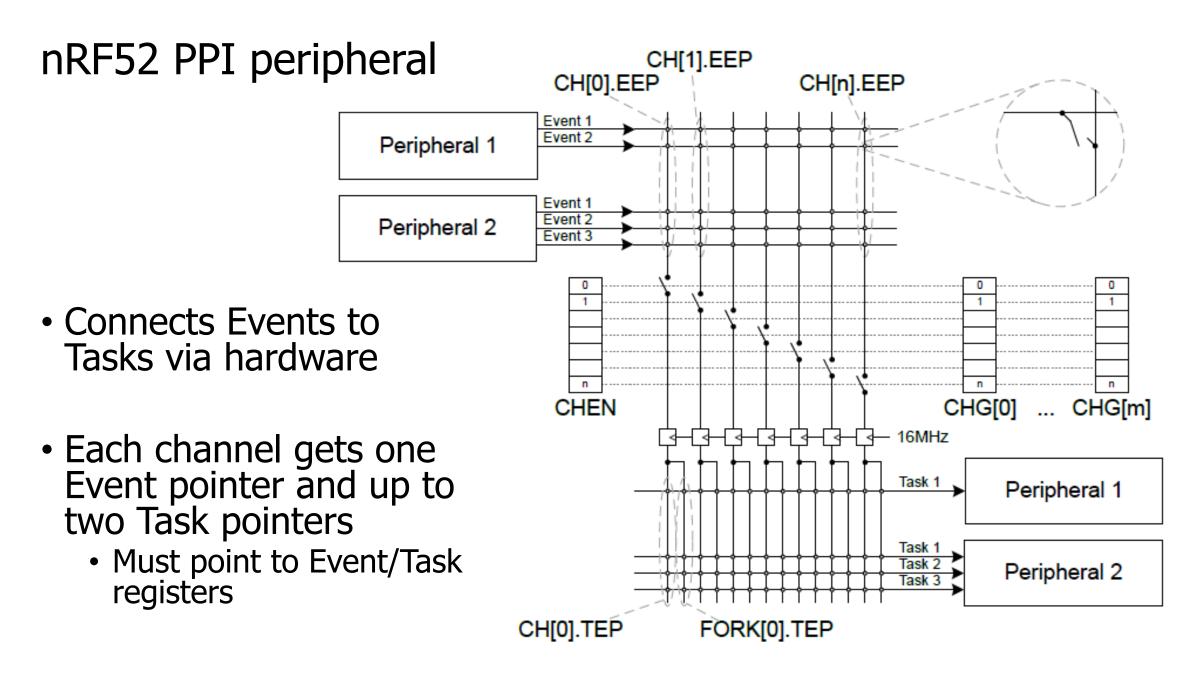
- DMA (Direct Memory Access)
 - Set up a pointer to memory and a length
 - Peripheral can load/store memory without processor's involvement
 - Usually use completion interrupt to wake processor
- PPI (Programmable Peripheral Interconnect)
 - Any Event can be tied to any Task within the nRF52
 - Allows for complicated actions to be chained together

nRF52 Tasks and Events

- Tasks are used to perform some operation
 - Often written to by software
- Events change value when some change in status occurs
 - Often used to trigger interrupts
- PPI peripheral can connect any TASK to any EVENT

Example: Timer peripheral

Register	Offset	Description
TASKS_START	0x000	Start Timer
TASKS_STOP	0x004	Stop Timer
TASKS_COUNT	0x008	Increment Timer (Counter mode only)
TASKS_CLEAR	0x00C	Clear time
TASKS_SHUTDOWN	0x010	Shut down timer
TASKS_CAPTURE[0]	0x040	Capture Timer value to CC[0] register
TASKS_CAPTURE[1]	0x044	Capture Timer value to CC[1] register
TASKS_CAPTURE[2]	0x048	Capture Timer value to CC[2] register
TASKS_CAPTURE[3]	0x04C	Capture Timer value to CC[3] register
TASKS_CAPTURE[4]	0x050	Capture Timer value to CC[4] register
TASKS_CAPTURE[5]	0x054	Capture Timer value to CC[5] register
EVENTS_COMPARE[0]	0x140	Compare event on CC[0] match
EVENTS_COMPARE[1]	0x144	Compare event on CC[1] match
EVENTS_COMPARE[2]	0x148	Compare event on CC[2] match
EVENTS_COMPARE[3]	0x14C	Compare event on CC[3] match
EVENTS_COMPARE[4]	0x150	Compare event on CC[4] match
EVENTS_COMPARE[5]	0x154	Compare event on CC[5] match



Example PPI use case

- Automatic high-speed ADC sampling
- Software configures and sleeps
 - ADC (buffer and enable)
 - Timer (prescaler, compare value, short from compare to clear, and start)
- PPI: When Timer fires (EVENTS_COMPARE[0]),
 - Sample ADC (TASKS_SAMPLE)
- PPI: When ADC buffer full (EVENTS_END),
 - Stop Timer (TASKS_STOP)
 - Fork: wake processor (via software interrupt from EGU)

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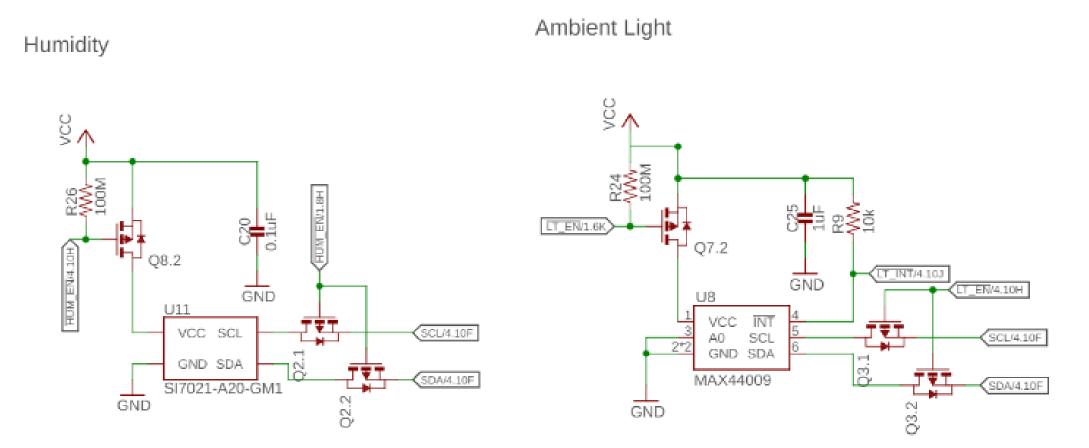
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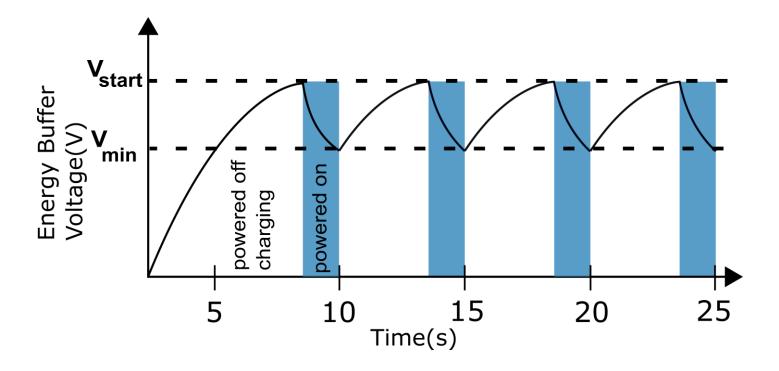
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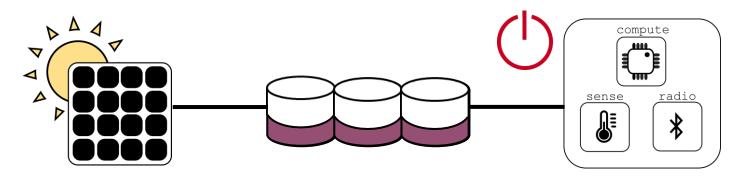
Reducing energy consumption even further

- If sleep isn't enough, you can power things off completely
 - Transistor can be used to turn off the sensor



Energy harvesting can lead to intermittent computing

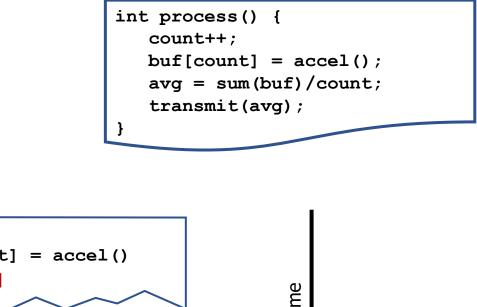




Disabling the microcontroller

- Even 2 μ A sleep current might be too much for energy harvesting
 - Can turn off microcontroller periodically
 - Enable it again once VCC returns
- Problem: how do you write software to deal with intermittency?
 - Run-to-completion with relatively quick code
 - Initialize, sample sensor, send packet, turn off again
 - Code checkpointing
 - Save state from code and restore when power resumes
 - Might be as little as which state the system is in, plus some samples
 - Might be as much as saving entire stack state
 - Needs low-energy, nonvolatile storage (FRAM or MRAM help!)

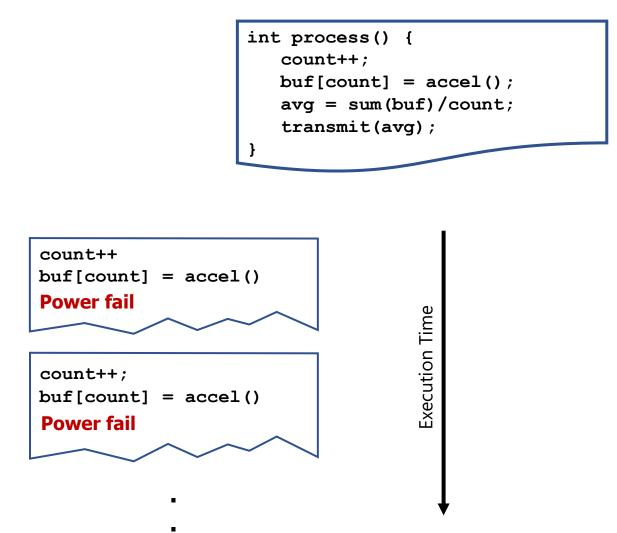
Programs may not finish



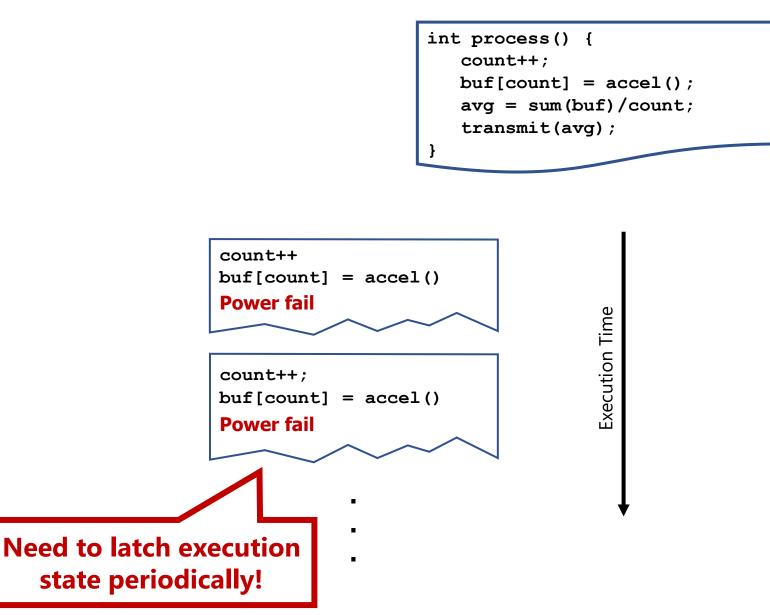
count++ buf[count] = accel() **Power fail**

Execution Time

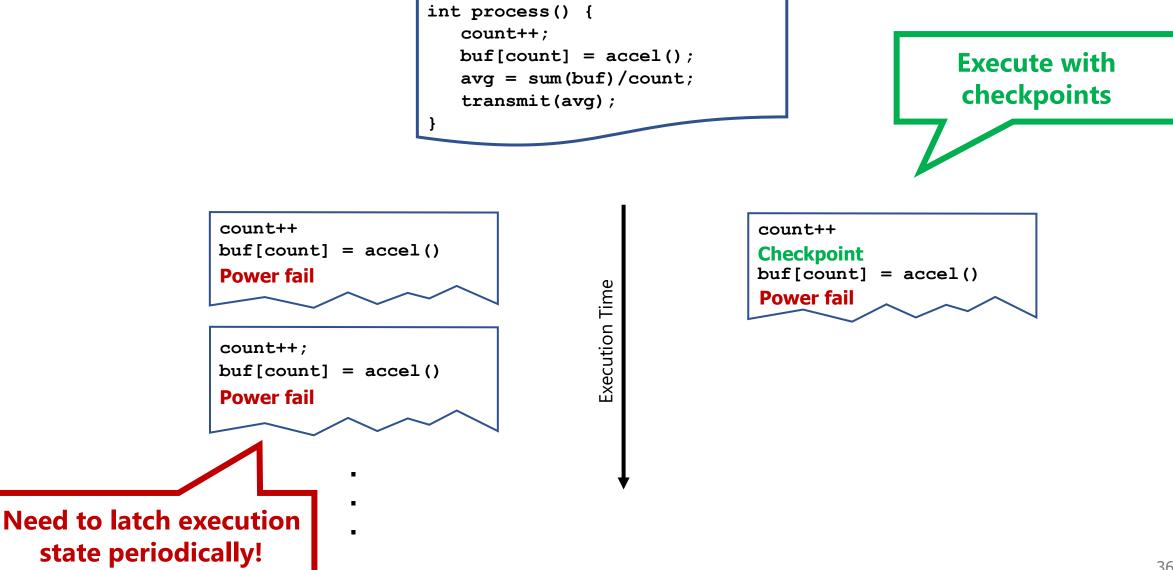
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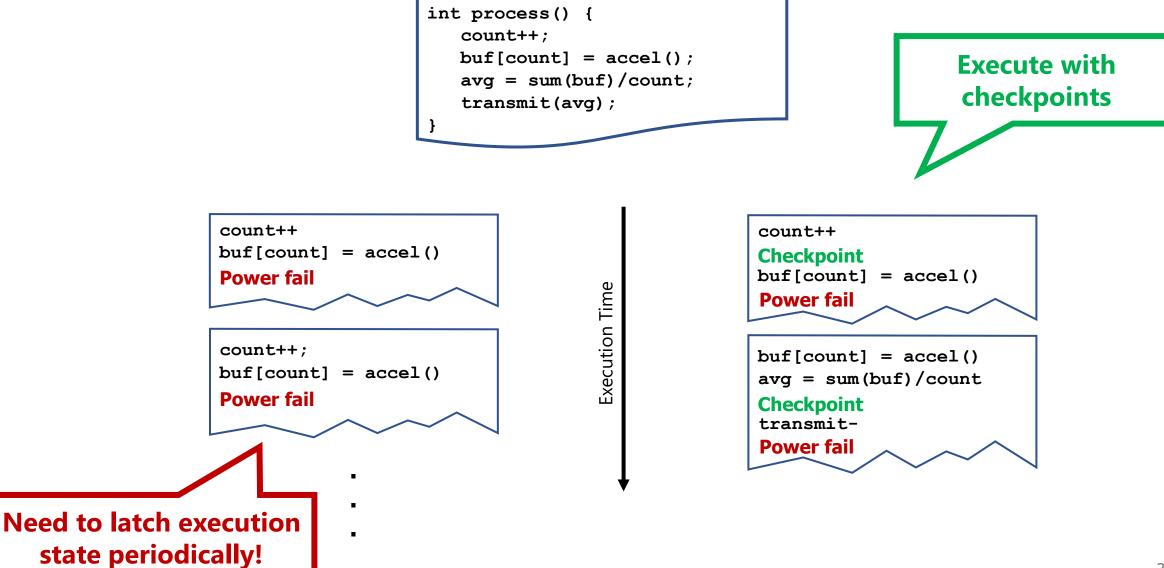
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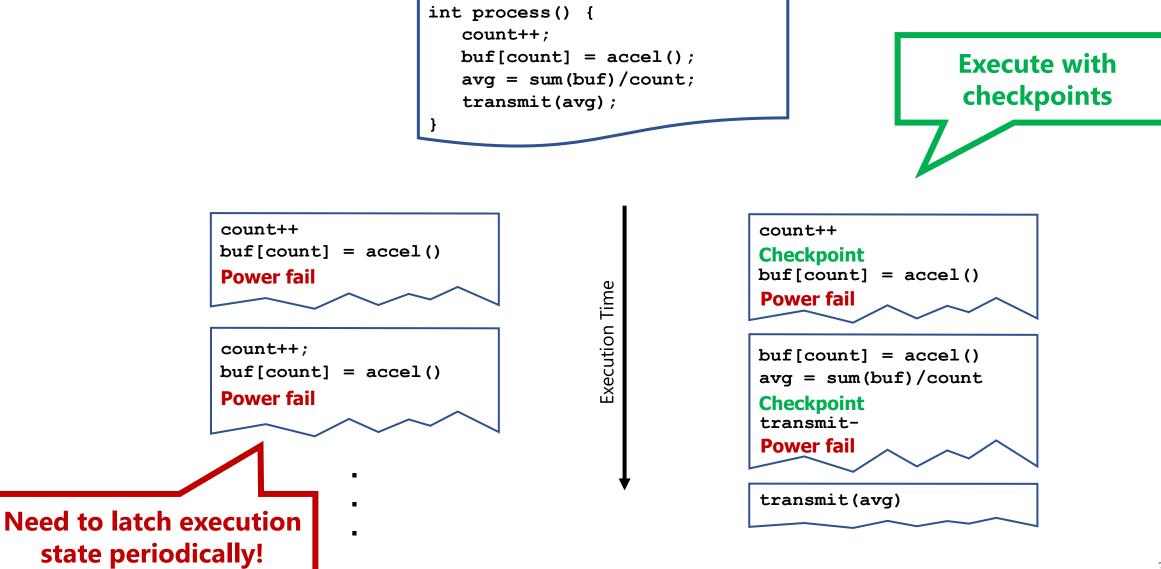
Checkpointing enables progress



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Checkpointing enables progress



Checkpointing goals

- Have the compiler automatically insert checkpoints as needed
 - Human doesn't have to think about them when programming
- Limit checkpointing overhead while maximizing forward progress
 - Checkpointing will take time to perform, so want to do it rarely
 - Rarer checkpoints mean more progress is lost in average outage
 - Need to compromise on the two based on available energy

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