Lecture 02 Microcontrollers

CE346 – Microprocessor System Design Branden Ghena – Fall 2021

Some slides borrowed from: Josiah Hester (Northwestern), Prabal Dutta (UC Berkeley)

Class Updates

- Reminder: no lab this Friday
 - I won't be there. Don't show up.
- My office hours are by request right now
 - · Will be posting an office hours schedule this weekend
- If you're still looking for permission to enroll:
 - Please come bug me after class
 - I believe there will be room for everybody

Today's Goals

- Explore microcontrollers
 - Their purpose
 - Their capabilities
 - Design tradeoffs
- Describe history and state-of-the-art for microcontrollers

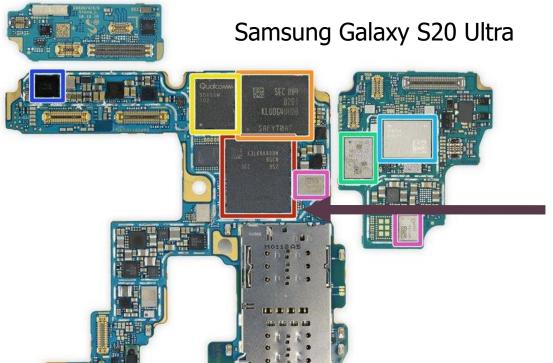
• Explore the microcontroller(s) on the Microbit

Outline

- Microcontroller Background
- Microcontroller Design
- Microcontroller History

Microbit microcontroller





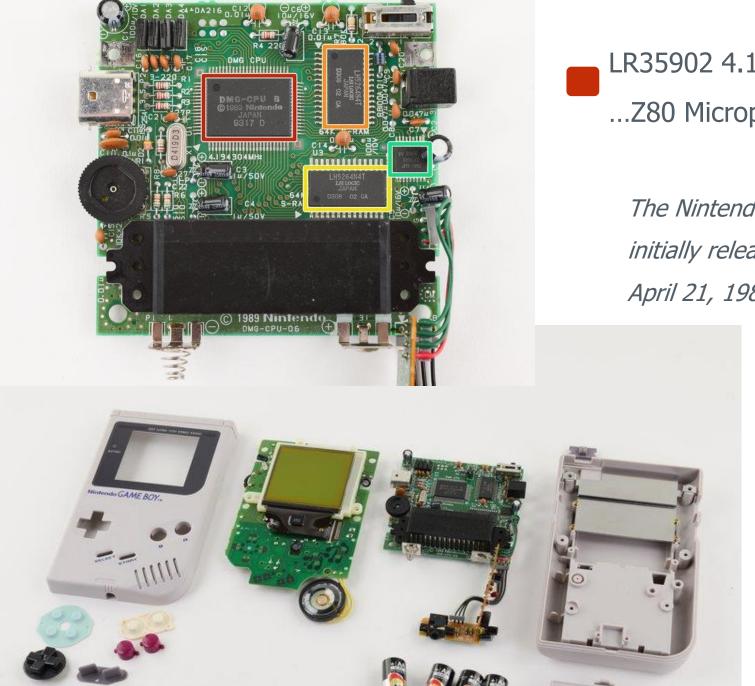
Samsung K3LK4K40BM-BGCN 12 GB LPDDR5

RAM layered over Qualcomm 865 SoC









LR35902 4.19 Mhz CPU

...Z80 Microprocessor

The Nintendo Game Boy was initially released in Japan on April 21, 1989

...computing everywhere!





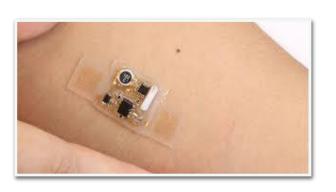












Categories of computer chips

- Microprocessor (MPU or Processor)
 - CPU + Bus/Pins
 - No memory or peripherals
- Microcontroller (MCU)
 - CPU + Pins + Memory + Peripherals
 - Peripherals: separate hardware units within chip
 - Often I/O interfaces
- System on a Chip (SoC)
 - Microcontroller + Extensive Peripherals
 - Example: Radios or ML Accelerators
 - Essentially multiple chips combined
- Evolution of increased complexity over time



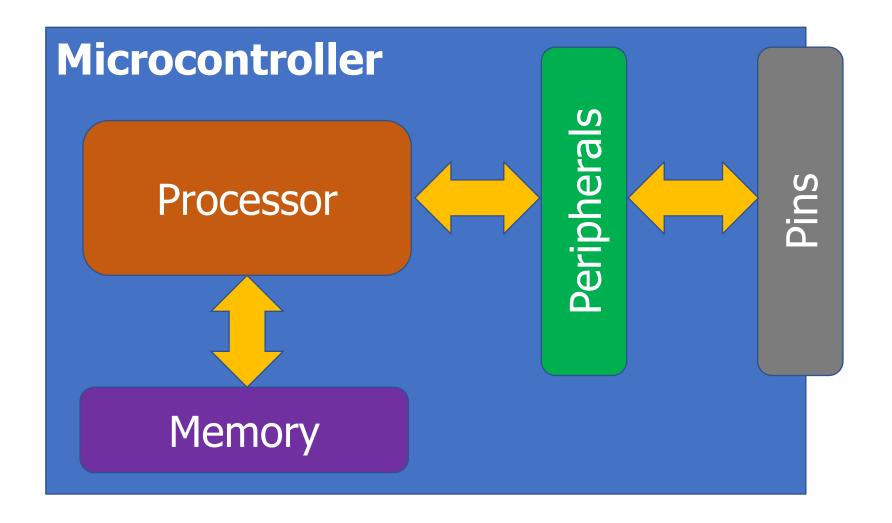


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Microbit microcontroller

Generic microcontroller block diagram



Processor

Microcontroller needs to execute software instructions

- Emphasis: simple and reliable
 - i.e. not x86 CISC
- Often simple, in-order, short-pipeline RISC architectures
 - Literally a three-stage pipeline you may have learned in CS361
- Many different ISAs are possible
 - Custom ISAs and ARM (ARMv7E-M) are both common

Reminder: Instruction Set Architecture

 ISA includes the actual instructions as well as the model for how the computer interacts with memory

 Does the ISA for a microcontroller matter if you're not programming in assembly? (and I promise we won't)

Reminder: Instruction Set Architecture

 ISA includes the actual instructions as well as the model for how the computer interacts with memory

- Does the ISA for a microcontroller matter if you're not programming in assembly?
 - Yes
 - Differences in instruction efficiency and amount are important
 - Differences in compiler support are VERY important

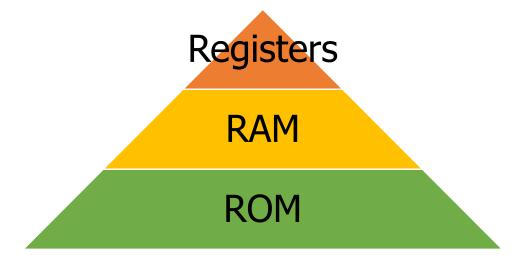
Processor design choices for embedded

- How many bits is the architecture?
 - 8-bit and 16-bit not uncommon
 - 64-bit is very rare (who has that much memory?)
- What instructions are supported?
 - Normal stuff yes
 - What about single-cycle multiply?
 - What about floating-point operations?
 - Vector instructions?

- How fast does it run?
 - 1-100 MHz is common on modern systems (faster is more energy cost)
 - Occasionally MUCH slower (think 32 KHz)

Memory

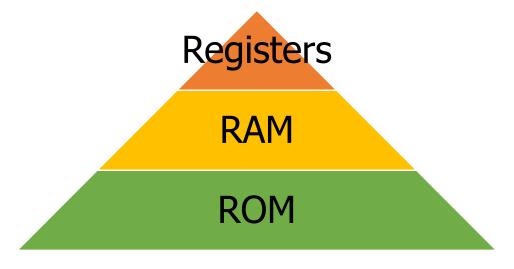
Embedded memory hierarchy



What's missing? Why?

Memory

Embedded memory hierarchy



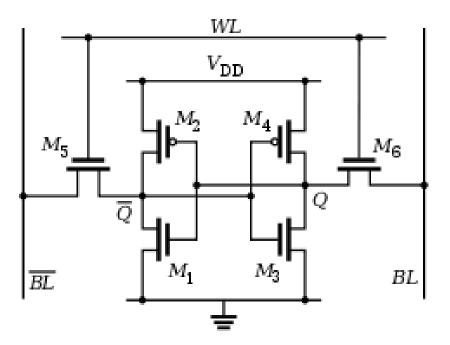
- What's missing? Why?
 - Cache
 - Makes timing unreliable

More modern microcontrollers often have optional instruction caches

Can be enabled by software

Volatile memory: SRAM

- Same design as registers in traditional computer systems
 - No need to refresh it -> lower energy costs
- Tradeoff:
 - More expensive
 - Physically larger



Non-Volatile memory: Flash (usually)

Same design as SSDs and Flash drives

- Memory is stored with no energy costs
 - Reading is lowish energy and quick
 - Writing is high energy and very slow
 - Writing also has to occur in blocks (e.g. 512 bytes)
- Concern: Flash has a limited lifetime ~10,000 writes
 - Only writing to Flash when you load code? Essentially forever
 - Recording data to Flash every second? 2.8 hours

SRAM (RAM) versus Flash (ROM) memory

- Size and time difference between non-volatile and volatile memory is significantly reduced from traditional computing
 - Non-volatile store 2-10x larger than volatile
 - Single-cycle RAM. Maybe two-cycles to Flash (to read)
- Major difference: energy and writability
 - SRAM is low-energy to read and write (no refresh needed)
 - Flash is lowish-energy to read, but very high energy to write
- Hierarchical structure is not enforced
 - Same address space for RAM and Flash (very different from traditional)
 - Run instructions right inside of Flash
 - Keep variables in RAM (or const variables in Flash)

Memory design choices

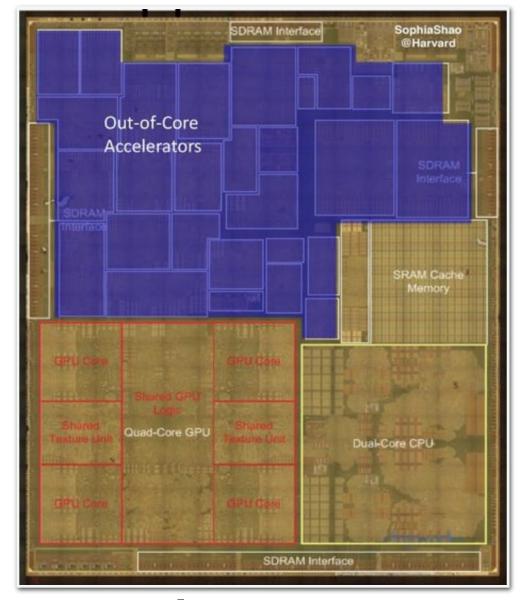
- How much memory can we fit without making it too high cost or too high power?
 - The answer has slowly increased over time
 - 15 years ago: 2 KB RAM 32 KB Flash
 - Today: 256 KB RAM 1 MB Flash
- How to provide memory safety?
 - Usually no virtual memory (all addresses are real addresses)
 - Nothing stops arbitrary memory overwriting
 - Modern systems: Memory Protection Unit
 - Specify a small number of ranges and permissions

Peripherals

- Hardware modules that perform some action
- Common examples
 - Control digital input and output pins
 - Read analog inputs
 - Send messages in a given wire protocol (UART, SPI, I2C)
 - Set and check timers
- Less common examples
 - Cryptography accelerators
 - Complicated wire protocols (USB, CAN)
 - Wireless radios (BLE, 802.15.4, WiFi)
- We'll spend most of class learning various peripherals

Peripheral design choices

- More peripherals mean more use cases
 - But also means more cost for the chip
 - Peripherals occupy silicon
 - Most peripherals will go unused for a given application...
- Flexibility within a given peripheral
 - One capability is easier to use
 - Many capabilities are more useful



Apple A8 SoC

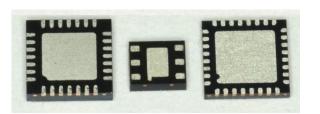
Pins

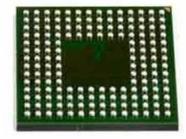
- Peripherals need to electrically connect to outside world
 - Attach to pins on the exterior of the chip



- More pins allow for more connections
 - At increased cost and size
- Pin layouts can add more pins for cheaper
 - But make soldering and debugging difficult







Internal connections to pins

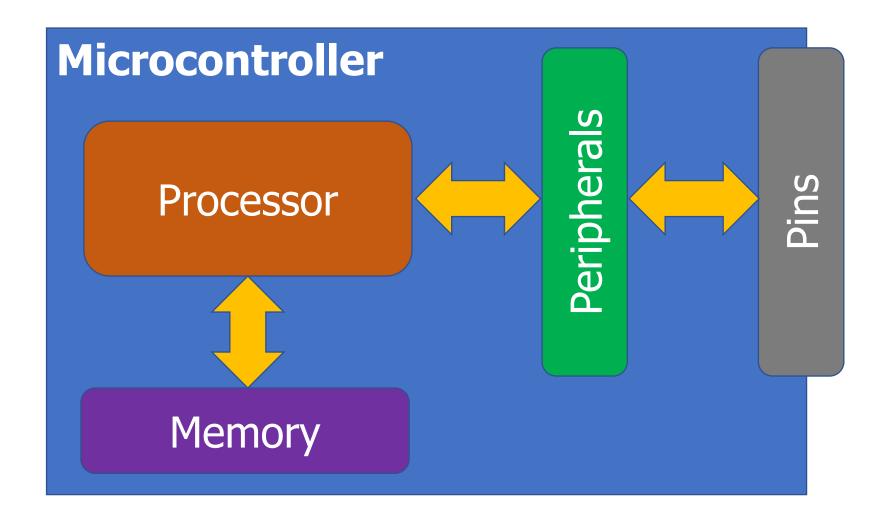
- Peripherals need to connect to external pins
 - Can any peripheral connect to any pin, or are there limited mappings?
 - Modern microcontrollers allow any-to-any connections

 Older MCUs had mapping tables and pin selection was more challenging

Table 3-1. 100-pin GPIO Controller Function Multiplexing (Sheet 1 of 4)

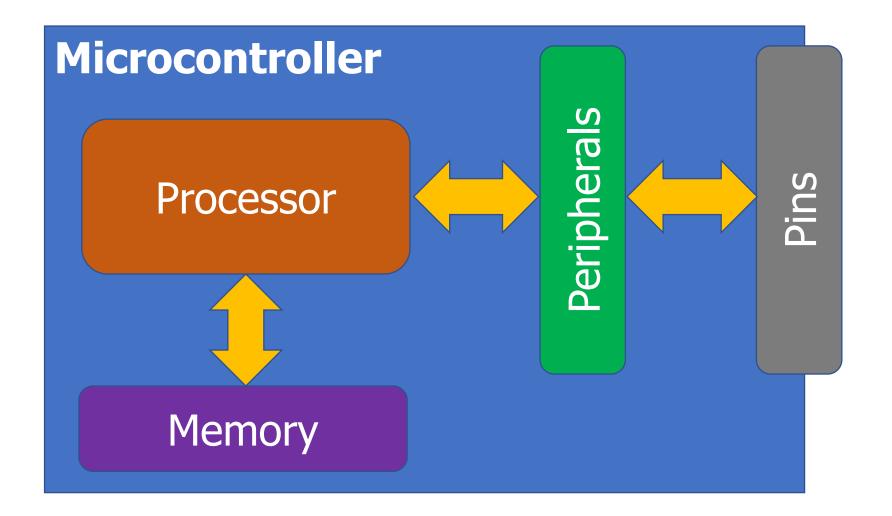
ATS AM4LC		ATSAM4LS		Pin	GPIO	Supply	GPIO Functions						
QFN	VFBGA	QFN	VFBGA				A	В	С	D	E	F	G
5	B9	5	B9	PA00	0	VDDIO							
6	B8	6	B8	PA01	1	VDDIO							
12	A7	12	A7	PA02	2	VDDIN	SCIF GCLK0	SPI NPCS0					CATB DIS
19	В3	19	В3	PA03	3	VDDIN		SPI MISO					
24	A2	24	A2	PA04	4	VDDANA	ADCIFE AD0	USART0 CLK	EIC EXTINT2	GLOC IN1			CATB SENSE0
25	A1	25	A1	PA05	5	VDDANA	ADCIFE AD1	USART0 RXD	EIC EXTINT3	GLOC IN2	ADCIFE TRIGGER		CATB SENSE1
30	СЗ	30	СЗ	PA06	6	VDDANA	DACC VOUT	USART0 RTS	EIC EXTINT1	GLOC IN0	ACIFC ACAN0		CATB SENSE2

What haven't we talked about?



What haven't we talked about?

- Power
- Programming
- Others?
 - Clocks
 - Antennas



Powering microcontrollers

- Usually require a specific voltage
 - E.g. 5 volts, 3.3 volts, 1.8 volts
 - Must be stable and supply enough current (or MCU "browns out")
 - Noisy power supply can be an issue
- Some microcontrollers have wider ranges of acceptable voltages
 - Need to pay attention to acceptable range on I/O though

Programming microcontrollers

- JTAG (Joint Test Action Group)
 - Hardware built into the microcontroller for testing purposes
 - Can arbitrarily read/write memory
 - Can single step process too, at runtime!
 - GDB can connect to it! (sort of)

Bootloaders

- Software runs on the microcontroller at boot that waits a short time for someone to contact it and upload code
 - Via I/O pins
- Convenient, but sometimes unreliable

Break + Open Question

 How little memory (RAM and/or ROM) can a computer have and still be useful?

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Older microcontrollers (90s-00s)

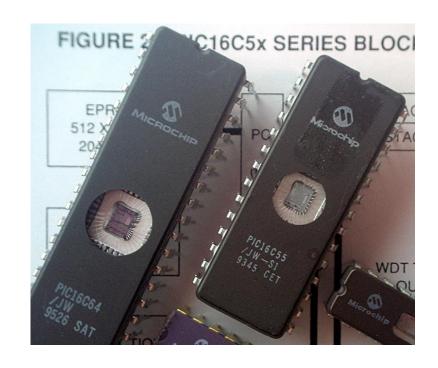
Focus: cheap, small computer systems

• PIC

- 8, 16, and 24-bit MIPs architecture
- PICAXE available with Basic interpreter

AVR

- 8-bit custom architecture (AVR architecture)
- Used in Arduinos
- AT Tiny 4: \$0.30 per unit
 - 4 I/O pins, 32 Bytes RAM, 512 Bytes ROM



More capable microcontrollers (00s-10s)

Focus: diversify into extreme low power and more capable systems

- MSP430
 - 16-bit custom architecture (MSP430 architecture)
 - Capable, but also extremely low power
 - <1 µA sleep current
- STM32, Atmel SAM series (Cortex-M0, M3, M4, M4F)
 - 32-bit ARM architecture (ARMv7)
 - Leverage success of ARM on smartphones
 - Every peripheral under the sun. Plus a variety of memory choices

Cortex M Series

A number of options for increasing capabilities

• In practice:

- Cortex-M0+ for low-end systems
- Coretx-M4 for high capability systems

ARM Cortex-M instruction variations

Arm Core	Cortex M0 ^[2]	Cortex M0+ ^[3]	Cortex M1 ^[4]	Cortex M3 ^[5]	Cortex M4 ^[6]	Cortex M7 ^[7]
ARM architecture	ARMv6-M ^[9]	ARMv6-M ^[9]	ARMv6-M ^[9]	ARMv7- M ^[10]	ARMv7E- M ^[10]	ARMv7E- M ^[10]
Computer architecture	Von Neumann	Von Neumann	Von Neumann	Harvard	Harvard	Harvard
Instruction pipeline	3 stages	2 stages	3 stages	3 stages	3 stages	6 stages
Thumb-1 instructions	Most	Most	Most	Entire	Entire	Entire
Thumb-2 instructions	Some	Some	Some	Entire	Entire	Entire
Multiply instructions 32x32 = 32-bit result	Yes	Yes	Yes	Yes	Yes	Yes
Multiply instructions 32x32 = 64-bit result	No	No	No	Yes	Yes	Yes
Divide instructions 32/32 = 32-bit quotient	No	No	No	Yes	Yes	Yes
Saturated instructions	No	No	No	Some	Yes	Yes
DSP instructions	No	No	No	No	Yes	Yes
Single-Precision (SP) Floating-point instructions	No	No	No	No	Optional	Optional
Double-Precision (DP) Floating-point instructions	No	No	No	No	No	Optional

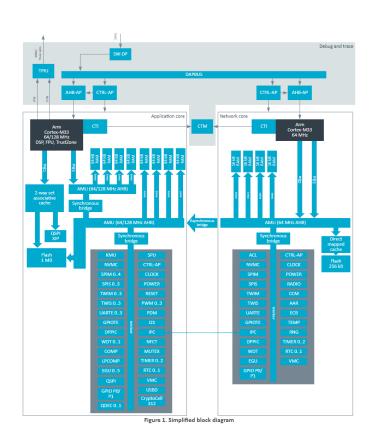
Modern system-on-chips (10s-?)

- Focus: increase memory and capability
 - Include radios in the same chip

- nRF51 and nRF52 series
 - 32-bit ARM microcontrollers (Cortex M)
 - Include 2.4 GHz radio: Bluetooth Low Energy and 802.15.4/Thread
- Others have followed this same path
 - TI CC26XX
 - Apollo3
 - STM32WL

Future microcontrollers

- Multi-core systems
 - Not for performance, but for separation of concerns
 - Run radio code on one core
 - Application code goes on the other core
 - Also allows BIG.little architecture
 - Higher performance core when interpreting data
 - Lower performance core for sampling sensors
 - nRF53 series is already doing this
 - But support is still nascent



Popular components rarely die

- Majority of popular older options still exist
 - Designers can trade off cost, capability, and efficiency alongside "modern features"

- Upgrading for an existing product is unlikely
 - Large cost, little benefit

- Example: Arduino still primarily uses AVR
 - Works just fine for its needs
 - Also releases new boards with nRF52s (Arduino Nano 33 BLE)



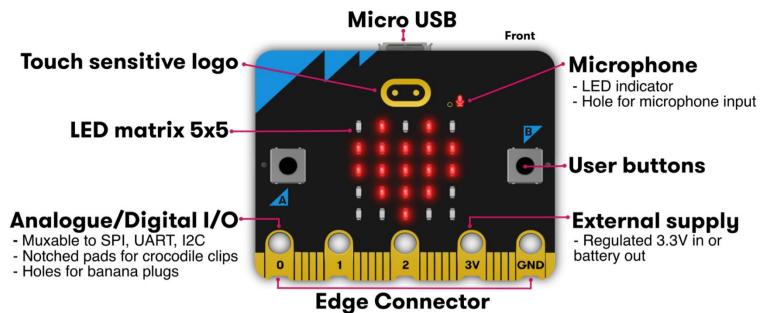
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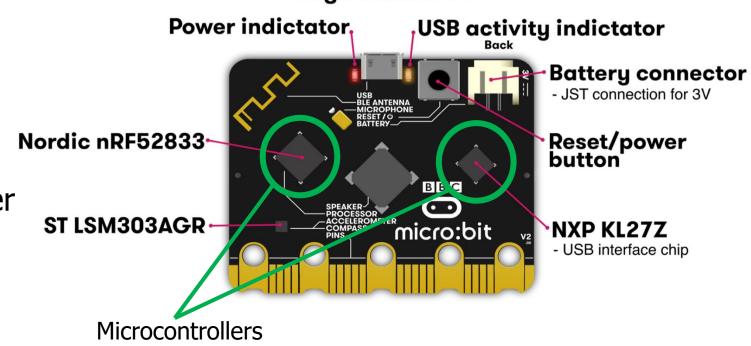
Microbit microcontroller

Micro:bit v2

- Circuit board
 - Entire thing
 - a.k.a "Dev Board"
 - a.k.a PCB (Printed Circuit Board)



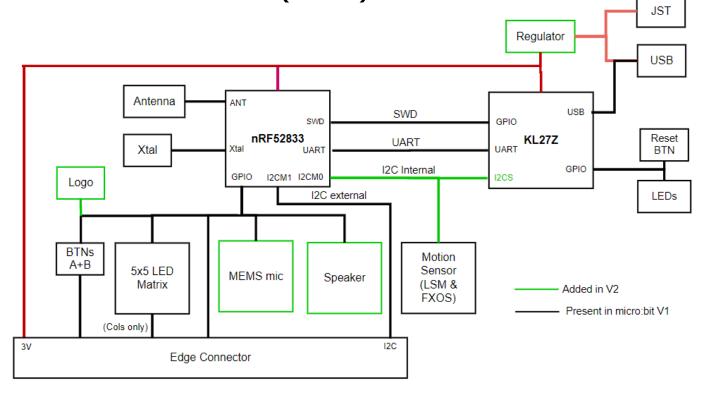
- Microcontroller
 - The computer on it
 - Microbit has two
 - One as a programmer
 - One for applications



KL27Z – Programmer on the Micro:bit v2

- 32-bit ARM Cortex-M0+ microcontroller
 - 48 MHz core, 16 KB RAM, 256 KB Flash
- Acts as a programming interface to nRF52833

Connects to USB and to JTAG (SWD)



nRF52833 – Microcontroller on the Micro:bit v2

- 32-bit ARM Cortex-M4F microcontroller
 - 64 MHz core, 128 KB RAM, 512 KB Flash
 - Floating point support
 - 2.4 GHz Radio: Bluetooth Low energy / 802.15.4
 - Various peripherals
 - ADC, PWM
 - I2C, UART, SPI, USB
 - RNG, 32-bit Timers, Watchdog, Temperature
 - Up to 42 I/O pins



To the datasheet!

- nRF52833 Product Specification
 - Online: https://infocenter.nordicsemi.com/index.jsp?topic=%2Fps_nrf52833%2Fke yfeatures https://infocenter.nordicsemi.com/index.jsp?topic=%2Fps_nrf52833%2Fke
 - PDF: https://infocenter.nordicsemi.com/pdf/nRF52833 PS v1.3.pdf

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